

Numerical Linear Algebra for Computational Science and Information Engineering

Jacobi-Davidson Methods

Nicolas Venkovic
nicolas.venkovic@tum.de

Chair of Computational Mathematics
School of Computation, Information and Technology
Technical University of Munich



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Motivation

- ▶ **Rayleigh-Ritz projections in Krylov subspaces** from Lanczos/Arnoldi procedures are very **effective to compute exterior eigenpairs**, provided the targeted eigenvalues are well-separated from the rest of the spectrum.
- ▶ In combination with a **shift-and-invert** spectral transformation, Rayleigh-Ritz projections in Krylov subspaces are also **efficient to compute interior eigenpairs** in the vicinity of a shift σ .
A proper implementation of shift-and-invert transformations requires an evaluation of the mapping $x \mapsto (A - \sigma I_n)^{-1}x$ at each iteration.
- ▶ The **Jacobi-Davidson** method is of particular interest when one cannot afford to evaluate $x \mapsto (A - \sigma I_n)^{-1}x$ with sufficient precision.
The Jacobi-Davidson method was proposed by Sleijpen and Van der Vorst (2000) on the basis of ideas from Jacobi (1845-46) and Davidson (1975).

Sleijpen, G. L., & Van der Vorst, H. A. (2000). A Jacobi-Davidson iteration method for linear eigenvalue problems. *SIAM review*, 42(2), 267-293.

Jacobi, C.G.J. (1845), Ueber eine neue Auflosungsart der bei der Methode der kleinsten Quadrate vorkommende linearen Gleichungen, *Astronom. Nachr.*, 297-306.

Jacobi, C. G. J. (1846). Über ein leichtes Verfahren die in der Theorie der Säcularstörungen vorkommenden Gleichungen numerisch aufzulösen. *J. Reine Angew. Math.*, 30, 51-94.

Davidson E. R. (1975). The iterative calculation of a few of the lowest eigenvalues and corresponding eigenvectors of large real symmetric matrices. *J. Comput. Phys.*, 17, 87-94.

Davidson method

Davidson method

- ▶ In the Davidson (1975) method, one is equipped with an **orthonormal basis** in the columns of $Q_k := [q_1, \dots, q_k] \in \mathbb{F}^{n \times k}$. A **Rayleigh-Ritz projection** in $\text{range}(Q_k)$ is deployed where $\text{range}(Q_k)$ is **not** a Krylov subspace. We search for $(\lambda, \hat{y}) \in \mathbb{F} \times \mathbb{F}^k$ such that

$$B_k \hat{y} = \lambda \hat{y}$$

where $B_k := Q_k^H A Q_k$. We then have a Rayleigh-Ritz pair (λ, y) in which $y := Q_k \hat{y}$, and a residual given by $r := Ay - \lambda y$.

- ▶ The purpose of the Davidson method is to **improve the Rayleigh-Ritz vector** y to decrease the residual norm $\|r\|_2$. For this, Davidson (1975) suggests to compute the **expansion vector** $t \in \mathbb{F}^n$ such that

$$(D_A - \lambda I_n)t = r$$

where $D_A \in \mathbb{F}^{n \times n}$ is the diagonal matrix formed with the diagonal A .

Davidson E. R. (1975). The iterative calculation of a few of the lowest eigenvalues and corresponding eigenvectors of large real symmetric matrices. *J. Comput. Phys.*, 17, 87–94.

Davidson method, cont'd₁

- The **expansion vector** t is then **orthogonalized** against q_1, \dots, q_k , **normalized** and **used to expand the search space**:

Solve for t such that $(D_A - \lambda I_n)t = r$

$t := \Pi^{(k)}t$ // $\Pi^{(k)}$ is a projector onto $\text{range}(Q_k)^\perp$

$q_{k+1} := t/\|t\|_2$

New Rayleigh-Ritz pairs can then be sought in $\text{range}(Q_{k+1})$.

- The Davidson method has shown great success to approximate **exterior eigenpairs** of **diagonally dominant**, *but not diagonal*, matrices A .
Indeed, if A is **diagonal**, then

$$t = (D_A - \lambda I_n)^{-1}r = (A - \lambda I_n)^{-1}(A - \lambda I_n)y = y \in \text{range}(Q_k)$$

so that the search space $\text{range}(Q_k)$ cannot be expanded with t .

Then the method **stagnates** and becomes unable to achieve convergence.

- If $D_A \propto I_n$, then the Davidson method is equivalent to Lanczos or Arnoldi.

Davidson E. R. (1975). The iterative calculation of a few of the lowest eigenvalues and corresponding eigenvectors of large real symmetric matrices. *J. Comput. Phys.*, 17, 87–94.

Davidson method, cont'd₂

- ▶ Although the Davidson method was originally applied to real symmetric matrices, it seamlessly applies to non-symmetric/Hermitian matrices. For **non-symmetric/Hermitian** matrices, the algorithm is as follows:

Algorithm 1 Davidson: $(A, q, k) \mapsto (\lambda, y)$

Davidson E. R. (1975). The iterative calculation of a few of the lowest eigenvalues and corresponding eigenvectors of large real symmetric matrices. *J. Comput. Phys.*, 17, 87–94.

Davidson method, cont'd₃

- ▶ For **Hermitian** matrices, the algorithm is as follows:

Algorithm 2 Davidson: $(A, q, k) \mapsto (\lambda, y)$

```

1: Allocate memory for  $Q_k \in \mathbb{F}^{n \times k}$  and  $B_k \in \mathbb{F}^{k \times k}$ 
2:  $q_1 := q / \|q\|_2$ 
3: for  $j = 1, \dots, k$  do
4:    $w := Aq_j$ 
5:    $B_k[1:j, j] := Q_j^H w$                                  $\triangleright B_k[j, 1:j-1] := B_k[1:j-1, j]^T$ 
6:   Solve for an exterior eigenpair  $(\lambda, \hat{y})$  of  $B_j$            $\triangleright B_j := B_k[1:j, 1:j]$ 
7:    $y := Q_j \hat{y}$ 
8:    $r := Ay - \lambda y$ 
9:   Solve for  $t$  such that  $(D_A - \lambda I_n)t = r$ 
10:   $t := \Pi^{(j)}t$                                           $\triangleright \Pi^{(j)}$  is a projector onto  $\text{range}(Q_j)^\perp$ 
11:   $q_{j+1} := t / \|t\|_2$ 

```

Although $\Pi^{(j)}$ is most commonly defined as a MGS procedure, CGS2 can also be used to mitigate potential stagnation, see van der Vorst (2002).

Davidson E. R. (1975). The iterative calculation of a few of the lowest eigenvalues and corresponding eigenvectors of large real symmetric matrices. *J. Comput. Phys.*, 17, 87–94.

van der Vorst, H. A. (2002). Computational methods for large eigenvalue problems.

Generalized Davidson (GD) method

Generalized Davidson method

- ▶ Some modifications of the Davidson method introduced by Morgan & Scott (1986) as well as Crouzeix et al. (1994) lead to variants collectively referred to as the **generalized Davidson (GD)** method.

Morgan & Scott (1986):

- A **general preconditioner** of the form $M - \vartheta I_n$ is used instead of the original $D_A - \lambda I_n$, **without requirement of positive-definiteness**.
- The aim is for $M - \vartheta I_n$ to **approximate** $A - \lambda I_n$ while allowing for **fast evaluation of** $r \mapsto (M - \vartheta I_n)^{-1}r$.
- The **preconditioner should not be too good** to avoid stagnation, i.e.,

$$M - \vartheta I_n = A - \lambda I_n \implies t := (M - \vartheta I_n)^{-1}r = y \in \text{range}(Q_k).$$

This **contradicts the common notion of preconditioner**.

- Numerical results reported with significantly **improved convergence** behaviors when **letting M be the tridiagonal form of A** and $\vartheta := \lambda$.
- Upon setting $\vartheta := \sigma$, one can **drive global convergence** toward some σ .

Morgan, R. B., & Scott, D. S. (1986). Generalizations of Davidson's method for computing eigenvalues of sparse symmetric matrices. *SIAM Journal on Scientific and Statistical Computing*, 7(3), 817-825.

Generalized Davidson method, cont'd₁

Morgan (1991):

- **Harmonic Ritz** pairs are used to yield even **faster convergence** towards **interior eigenpairs**.

Crouzeix et al. (1994):

- Several eigenpairs are sought at the same time and several vectors are incorporated into each search space expansion, leading to a **block implementation**.
- A **maximum search space dimension** is introduced, triggering periodic **restarts** of the iterative method.
- **Restarting** of the GD method **renders convergence dependent on positive-definiteness of the preconditioners**.

Sadkane (1993):

- **Extension** of the GD method to **real non-symmetric matrices**.

Morgan, R. B. (1991). Computing interior eigenvalues of large matrices. *Linear Algebra and its Applications*, 154, 289-309.

Crouzeix, M., Philippe, B., & Sadkane, M. (1994). The Davidson method. *SIAM Journal on Scientific Computing*, 15(1), 62-76.

Sadkane, M. (1993). Block-Arnoldi and Davidson methods for unsymmetric large eigenvalue problems. *Numerische Mathematik*, 64, 195-211.

Generalized Davidson method, cont'd₂

- ▶ The computation of Rayleigh-Ritz pairs after the generalized Davidson (GD) method is as follows:

Algorithm 3 GD: $(A, q, k) \mapsto (\lambda, y)$

```

1: Allocate memory for  $Q_k, W_k \in \mathbb{F}^{n \times k}$  and  $B_k \in \mathbb{F}^{k \times k}$ 
2:  $q_1 := q/\|q\|_2$ 
3: for  $j = 1, \dots, k$  do
4:    $w_j := Aq_j$ 
5:    $B_k[1:j, j] := Q_j^H w_j$ ,  $B_k[j, 1:j-1] := q_j^H W_{j-1}$ 
6:   Solve for an exterior eigenpair  $(\lambda, \hat{y})$  of  $B_j$                                  $\triangleright B_j := B_k[1:j, 1:j]$ 
7:    $y := Q_j \hat{y}$ 
8:    $r := Ay - \lambda y$ 
9:   Solve for  $t$  such that  $(M - \lambda I_n)t = r$ 
10:   $t := \Pi^{(j)} t$                                           $\triangleright \Pi^{(j)}$  is a projector onto  $\text{range}(Q_j)^\perp$ 
11:   $q_{j+1} := t/\|t\|_2$ 

```

Generalized Davidson method, cont'd₃

- ▶ For a **harmonic Ritz pair** (λ, y) with respect to a search space range (Q_k) , there exists $\hat{y} \in \mathbb{F}^k$ such that $y = Q_k \hat{y}$ and

$$G_1 \hat{y} = \lambda G_2^H \hat{y}$$

where $G_1 := ((A - \sigma I_n)Q_k)^H(A - \sigma I_n)Q_k$ and $G_2 := Q_k^H(A - \sigma I_n)Q_k$.

If A is non-Hermitian, a **basic implementation** of the harmonic GD method is as follows:

Algorithm 4 Basic harmonic GD: $(A, q, \sigma, k) \mapsto (\lambda, y)$

Jacobi methods

Orthogonal complement corrections

► Jacobi orthogonal complement correction (JOCC):

Jacobi (1845) considered an eigenvalue problem as a linear system of equations for which an iterative solver, e.g., Jacobi iteration, is used as a means to generate a **sequence of orthogonal complement corrections to a given approximate eigenvector**.

- Suppose we have a **strongly diagonally dominant** matrix A , of which $\alpha := a_{11}$ is the largest element.
- Then (α, e_1) is an **approximation** of the **largest eigenpair** (θ, z) of A .
- In matrix notation, the JOCC approach is as follows. Consider

$$A \left(e_1 + \begin{bmatrix} 0 \\ w \end{bmatrix} \right) = \theta \left(e_1 + \begin{bmatrix} 0 \\ w \end{bmatrix} \right)$$
$$\begin{bmatrix} \alpha & c^T \\ b & F \end{bmatrix} \left(e_1 + \begin{bmatrix} 0 \\ w \end{bmatrix} \right) = \theta \left(e_1 + \begin{bmatrix} 0 \\ w \end{bmatrix} \right)$$

where $[0 \ w^T]^T$ is an **orthogonal complement correction** to the approximate eigenvector e_1 .

Jacobi, C.G.J. (1845), Ueber eine neue Auflosungsart der bei der Methode der kleinsten Quadrate vorkommende linearen Gleichungen, Astronom Nachr, 297-306.

Orthogonal complement corrections, cont'd

- The eigenvalue problem leads to the following equations:

$$\lambda = \alpha + c^T w$$

$$(F - \lambda I_n)w = -b$$

which Jacobi proceeded to solve with the following iteration:

$$\lambda_k := \alpha + c^T w_k$$

$$(D_F - \lambda_k I_n)w_{k+1} = (D_F - F)w_k - b$$

with $w_1 := 0$.

- This later became known as the **Jacobi iteration**.
- Although λ_k is not a Rayleigh-Ritz value, it is nevertheless an approximation of the largest eigenvalue θ .

► As the **JOCC** approach is **best-suited for strongly diagonally dominant matrices**, Jacobi (1846) coupled this approach with a **set of rotations** whose application **makes the matrix more diagonally dominant**.

Jacobi, C.G.J. (1845). Ueber eine neue Auflosungsart der bei der Methode der kleinsten Quadrate vorkommende linearen Gleichungen, Astronom. Nachr, 297-306.

Jacobi, C. G. J. (1846). Über ein leichtes Verfahren die in der Theorie der Säcularstörungen vorkommenden Gleichungen numerisch aufzulösen. J. Reine Angew. Math., 30, 51–94.

Jacobi-Davidson method

JOCC by Sleijpen and van der Vorst (1996)

- ▶ Sleijpen and van der Vorst (2000) revisited the JOCC approach in the more general setting where an arbitrary iterate $y_j \in \mathbb{F}^n$ is known as an approximate eigenvector of $A \in \mathbb{F}^{n \times n}$.
JOCC's adaptation to this more general context lies in setting a correction $\delta \in \mathbb{F}^n$ to y_j with unit norm such that

$$A(y_j + \delta) = \theta(y_j + \delta), \quad \delta \perp y_j \quad (1)$$

where θ is the wanted eigenvalue of A .

Eq. (1) can be decomposed into two parts, along and orthogonal to y_j :

- First, the **part parallel to y_j** , given by

$$y_j y_j^H A(y_j + \delta) = \theta y_j y_j^H (y_j + \delta)$$

is such that $\boxed{\vartheta_j + y_j^H A \delta = \theta}$ where $\boxed{\vartheta_j := y_j^H A y_j}$ is the **corrected eigenvalue estimate**.

JOCC by Sleijpen and van der Vorst (1996), cont'd

- Second, the **part orthogonal to y_j** , given by

$$(I_n - y_j y_j^H) A (y_j + \delta) = \theta (I_n - y_j y_j^H) (y_j + \delta)$$

$$\begin{aligned} \text{is such that } (I_n - y_j y_j^H) (A - \theta I_n) \delta &= (I_n - y_j y_j^H) (-A y_j + \theta y_j) \\ &= - (I_n - y_j y_j^H) A y_j \\ &= - (A y_j - \vartheta_j y_j) =: -r_j. \end{aligned}$$

Since $\delta \perp y_j$, we have $\delta = (I_n - y_j y_j^H) \delta$, and we obtain:

$$(I_n - y_j y_j^H) (A - \theta I_n) (I_n - y_j y_j^H) \delta = -r_j$$

where θ , which is **unknown**, is replaced by ϑ_j to yield the **Jacobi-Davidson correction equation** given by:

$$\boxed{(I_n - y_j y_j^H) (A - \vartheta_j I_n) (I_n - y_j y_j^H) \delta = -r_j}.$$

Note that $r_j^H y_j = y_j^H A y_j - \vartheta_j = 0 \implies r_j \perp y_j$ so that **this equation is consistent as long as $A - \vartheta_j I_n$ is not singular**.

Sleijpen, G. L., & Van der Vorst, H. A. (1996). A Jacobi-Davidson iteration method for linear eigenvalue problems. SIAM review, 42(2), 267-293.

Exact solution of the Jacobi-Davidson correction equation

- The Jacobi-Davidson correction equation is such that

$$(I_n - y_j y_j^H)(A - \vartheta_j I_n)\delta = -r_j, \quad \delta \perp y_j$$

$$(A - \vartheta_j I_n)\delta - y_j y_j^H(A - \vartheta_j I_n)\delta = -r_j$$

so that $(A - \vartheta_j I_n)\delta = \alpha y_j - r_j$ where $\alpha := y_j^H(A - \vartheta_j I_n)\delta$. If ϑ_j is not an exact eigenvalue of A , then we get

$$\delta = \alpha(A - \vartheta_j I_n)^{-1}y_j - (A - \vartheta_j I_n)^{-1}r_j.$$

And from the orthogonality condition $y_j \perp \delta$, we get

$$\alpha = \frac{y_j^H(A - \vartheta_j I_n)^{-1}r_j}{y_j^H(A - \vartheta_j I_n)^{-1}y_j}.$$

Then, we set: $y_{j+1} := y_j + \delta$

$$\begin{aligned} &= y_j + \alpha(A - \vartheta_j I_n)^{-1}y_j - (A - \vartheta_j I_n)^{-1}r_j \\ &= \alpha(A - \vartheta_j I_n)^{-1}y_j \end{aligned}$$

which corresponds to a **Rayleigh quotient iteration**.

Iterative solve of the Jacobi-Davidson equation

- ▶ In practice, the J-D correction equation is only solved approximately, typically using either MINRES (Paige & Saunders, 1975) when A is symmetric/Hermitian, or GMRES (Saad & Schultz, 1986) or even BiCGSTAB (Van der Vorst, 1992), when A is non-Hermitian.
- ▶ At every step j of the iteration, one has to solve a linear system with a varying shift.
- ▶ Based on the decomposition of the orthogonal correction δ presented by Sleijpen and van der Vorst (2000), a preconditioning of the following form is proposed:

$$r \mapsto \alpha M^{-1}y_j + M^{-1}r \text{ where } \alpha := \frac{y_j^H M^{-1} r}{y_j^H M^{-1} y_j},$$

in which M serves as an approximation of $A - \vartheta_j I_n$.

Paige, C.C. & M.A. Saunders (1975). Solution of sparse indefinite systems of linear equations. SIAM, J Numer Anal 12, 617-629.

Saad, Y. & Schultz M.H. (1986). GMRES: a generalized minimal residual algorithm for solving nonsymmetric linear systems, SIAM J Sci Statist Comput 7, 856-869.

van der Vorst, H. A. (1992). Bi-CGSTAB: A fast and smoothly converging variant of Bi-CG for the solution of nonsymmetric linear systems. SIAM Journal on Scientific and Statistical Computing, 13(2):631-644.

Sleijpen, G. L. G. & van der Vorst, H. A. (2000). A Jacobi-Davidson iteration method for linear eigenvalue problems, SIAM Review, 42(2), 267-293.

Jacobi-Davidson algorithm with Rayleigh-Ritz projections

- ▶ Applying the Jacobi-Davidson (J-D) method to Rayleigh-Ritz projections, we obtain the following algorithm:

Algorithm 5 J-D: $(A, q, k) \mapsto (\lambda, y)$

- 1: Allocate memory for $Q_k, W_k \in \mathbb{F}^{n \times k}$ and $B_k \in \mathbb{F}^{k \times k}$
- 2: $\tilde{t} := q$
- 3: **for** $j = 1, \dots, k$ **do**
- 4: $\tilde{t} := \Pi^{(j-1)} \tilde{t}$ $\triangleright \Pi^{(j)}$ is a projector onto $\text{range}(Q_j)^\perp$
- 5: $q_j := \tilde{t} / \|\tilde{t}\|_2$
- 6: $w_j := Aq_j$
- 7: $B_k[1:j, j] := Q_j^H w_j, B_k[j, 1:j-1] := q_j^H W_{j-1}$
- 8: Solve for eigenpair (λ, \hat{y}) of B_j
- 9: $y := Q_j \hat{y}$
- 10: $r := W_j \hat{y}_j - \lambda y$
- 11: Solve for $\tilde{t} \approx t$ such that $(I_n - y_j y_j^H)(A - \lambda I_n)(I_n - y_j y_j^H)t = r$

Jacobi-Davidson algorithm with harmonic Ritz projections

- ▶ We saw in previous lectures that Rayleigh-Ritz projections converge first towards exterior eigenpairs, generally offering only poor approximations of interior pairs.
- ▶ Harmonic Ritz projections are the method of choice to find better approximations of interior eigenpairs.

Jacobi-Davidson algorithm with harmonic Ritz projections, cont'd

- ▶ Similarly as we previously saw for the GD method, the use of harmonic Ritz projections is recommended when trying to approximate interior eigenpair:

Algorithm 6 Basic harmonic J-D: $(A, q, \sigma, k) \mapsto (\lambda, y)$

```

1: Allocate memory for  $Q_k, W_k \in \mathbb{F}^{n \times k}$  and  $G_1, G_2 \in \mathbb{F}^{k \times k}$ 
2:  $\tilde{t} := q$ 
3: for  $j = 1, \dots, k$  do
4:    $\tilde{t} := \Pi^{(j-1)}\tilde{t}$                                  $\triangleright \Pi^{(j)}$  is a projector onto  $\text{range}(Q_j)^\perp$ 
5:    $q_j := \tilde{t}/\|\tilde{t}\|_2$ 
6:    $w_j := (A - \sigma I_n)q_j$ 
7:    $G_1[1:j, j] := W_j^H w_j$                           $\triangleright G_1[j, 1:j-1] := G_1[1:j-1, j]^H$ 
8:    $G_2[1:j, j] := Q_j^H w_j$ ,  $G_2[j, 1:j-1] := q_j^H W_{j-1}$ 
9:   Solve for eigenpair  $(\lambda, \hat{y})$  of  $G_2[1:j, 1:j]^{-H} G_1[1:j, 1:j]$  closest to 0
10:   $y := Q_j \hat{y}$ 
11:   $\delta_\rho := \hat{y}^H G_2 \hat{y}$ ,  $\rho := \sigma + \delta_\rho$ 
12:   $r := W_j \hat{y}_j - \delta_\rho y$ 

```