

Effect of Morphological Idealization on Mean-Field Self-Consistent Homogenization of Polycrystals

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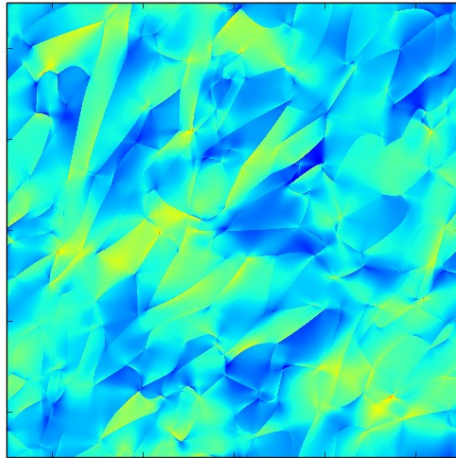


May 2016

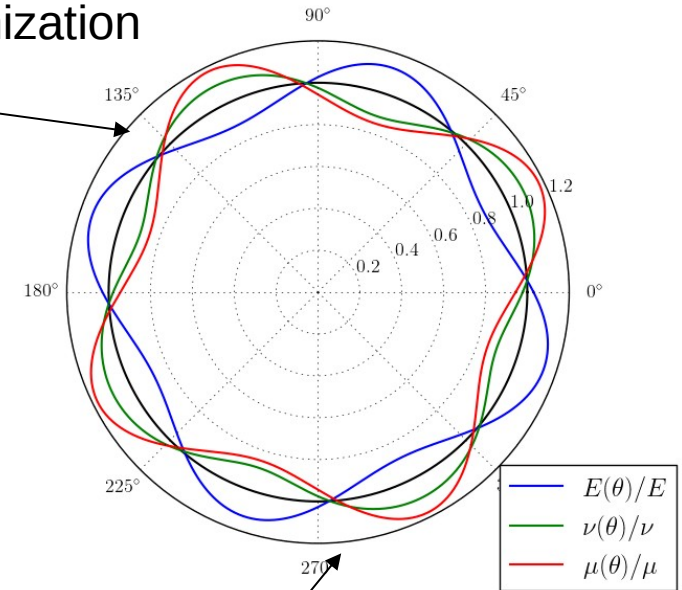
Motivation and objective

- Identify best idealization

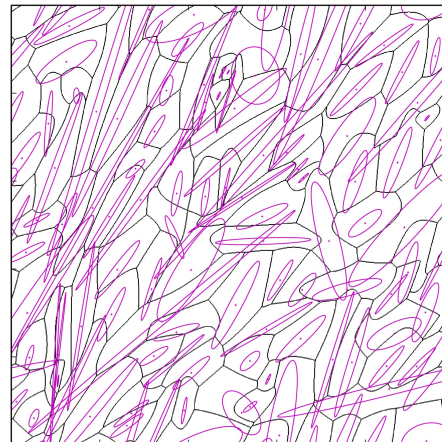
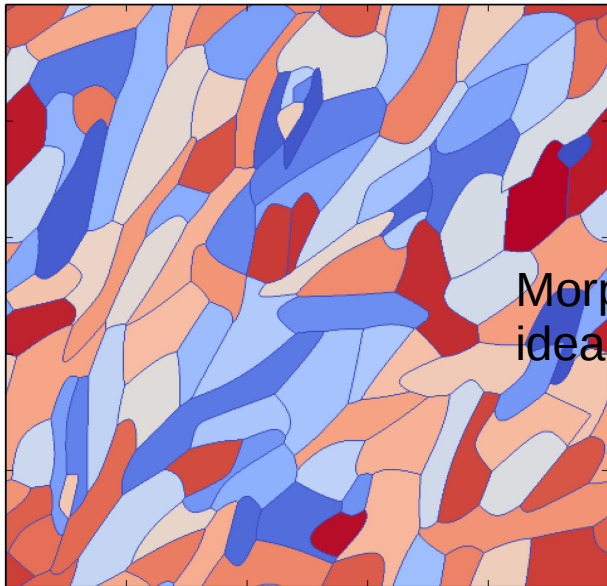
Full-field simulation



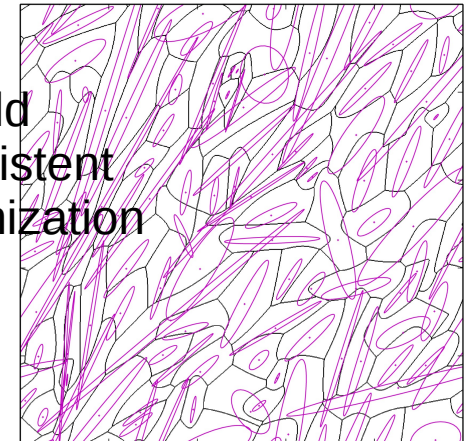
Numerical homogenization



Morphology idealization



Mean-field self-consistent homogenization



Outline

- Morphological characterization of single grains
- Numerical homogenization
- Self-consistent homogenization
- Shape idealization
- Comparison of SC estimates of elastic stiffness

Single grain morphology characterization

Single grains are characterized using Minkowski tensors:

Measures of mass distribution:

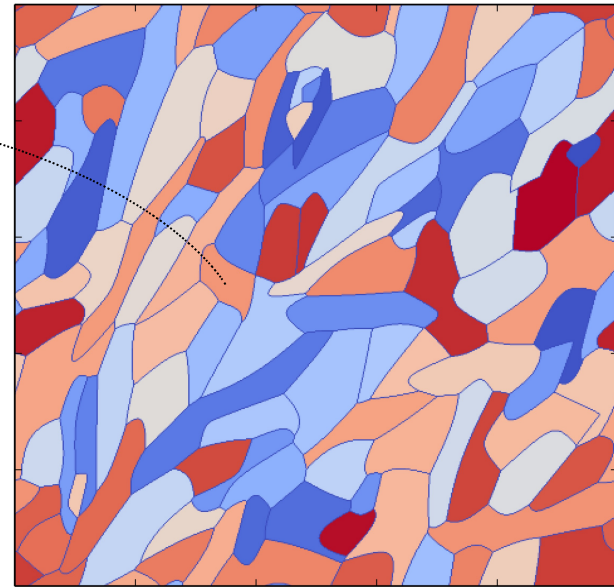
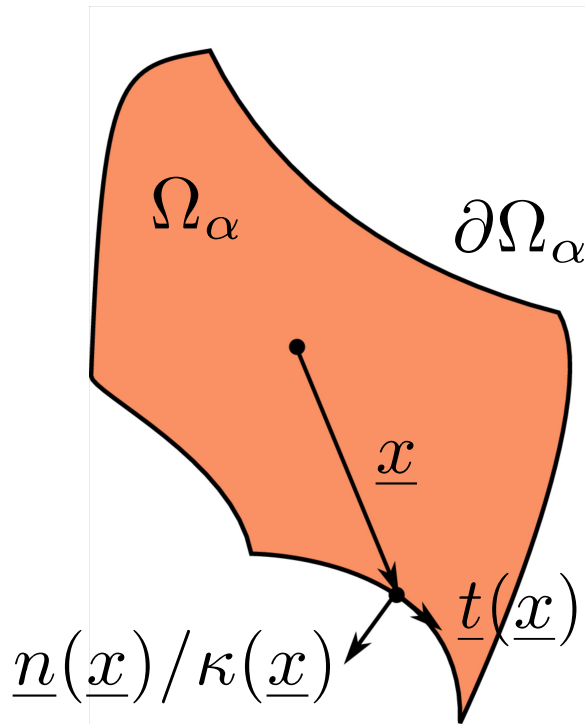
$$\mathcal{W}_0^{r,0} = \int_{\Omega_\alpha} \underline{x}^{\otimes r} dV$$

Measures of surface distribution:

$$\mathcal{W}_1^{r,s} = \int_{\partial\Omega_\alpha} \underline{x}^{\otimes r} \odot [\underline{n}(\underline{x})]^{\otimes s} dS$$

Curvature-weighted measures of surface distribution:

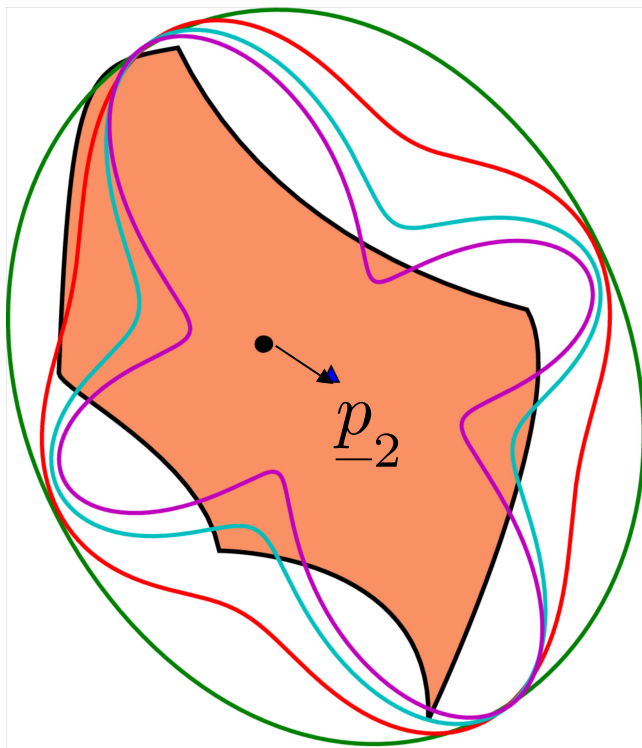
$$\mathcal{W}_2^{r,s} = \int_{\partial\Omega_\alpha} \kappa(\underline{x}) \underline{x}^{\otimes r} \odot [\underline{n}(\underline{x})]^{\otimes s} dS$$



Single grain morphology characterization

For a single grain, there are many different Minkowski tensors of a given order, most of which are independent.

Example: Reynolds glyphs of curvature-weighted tensors $\mathcal{W}_2^{r,0}$:



— (green)	$\mathcal{P}[*\mathcal{W}_2^{2,0}] + \underline{p}_2$
— (red)	$\mathcal{P}[*\mathcal{W}_2^{4,0}] + \underline{p}_2$
— (cyan)	$\mathcal{P}[*\mathcal{W}_2^{6,0}] + \underline{p}_2$
— (purple)	$\mathcal{P}[*\mathcal{W}_2^{8,0}] + \underline{p}_2$

Question: What types and orders of Minkowski tensors are relevant and sufficient metrics for a grain?

Classic FFT solver

Following Moulinec and Suquet (1998), we have:

- 1 $\hat{\mathbf{N}}(\underline{k}) = [\underline{k} \mathbb{C}_0 \underline{k}]^{-1} \quad \forall \underline{k} \neq \underline{0}$
 - 2 $\hat{\mathbf{\Gamma}}(\underline{k}) = \underline{k} \odot \hat{\mathbf{N}}(\underline{k}) \odot \underline{k} \quad \forall \underline{k} \neq \underline{0}, \hat{\mathbf{\Gamma}}(\underline{0}) = \mathbb{O}$
 - 3 ${}^0\boldsymbol{\varepsilon}(\underline{y}) = \langle \boldsymbol{\varepsilon} \rangle, \quad {}^0\boldsymbol{\sigma}(\underline{y}) = \mathbb{C}(\underline{y}) : {}^0\boldsymbol{\varepsilon}(\underline{y})$
 - 4 $m = 0, \quad \epsilon = 2\epsilon_{tol}$
 - 5 while $\epsilon > \epsilon_{tol}$:
 - 6 ${}^m\boldsymbol{\tau}(\underline{y}) = {}^m\boldsymbol{\sigma}(\underline{y}) - \mathbb{C}_0 : {}^m\boldsymbol{\varepsilon}(\underline{y})$
 - 7 ${}^m\Delta\hat{\boldsymbol{\varepsilon}}(\underline{k}) = -\hat{\mathbf{\Gamma}}(\underline{k}) : \mathcal{F}\{{}^m\boldsymbol{\tau}(\underline{y})\}(\underline{k})$
 - 8 ${}^{m+1}\boldsymbol{\varepsilon}(\underline{y}) = \langle \boldsymbol{\varepsilon} \rangle + \mathcal{F}^{-1}\{{}^m\Delta\hat{\boldsymbol{\varepsilon}}(\underline{k})\}(\underline{y})$
 - 9 ${}^{m+1}\boldsymbol{\sigma}(\underline{y}) = \mathbb{C}(\underline{y}) : {}^{m+1}\boldsymbol{\varepsilon}(\underline{y})$
 - 10 $\epsilon = {}^{m+1}\epsilon$
- Version 1**

Discrete system:

$$x_1 = \{iL_x/N_x \mid i = 0, \dots, N_x - 1\}$$

$$x_2 = \{iL_y/N_y \mid i = 0, \dots, N_y - 1\}$$

$$k_1 = \left\{ \frac{i - N_x/2}{L_x} \mid i = 0, \dots, N_x - 1 \right\}$$

$$k_2 = \left\{ \frac{i}{L_y} \mid i = 0, \dots, N_y/2 \right\}$$

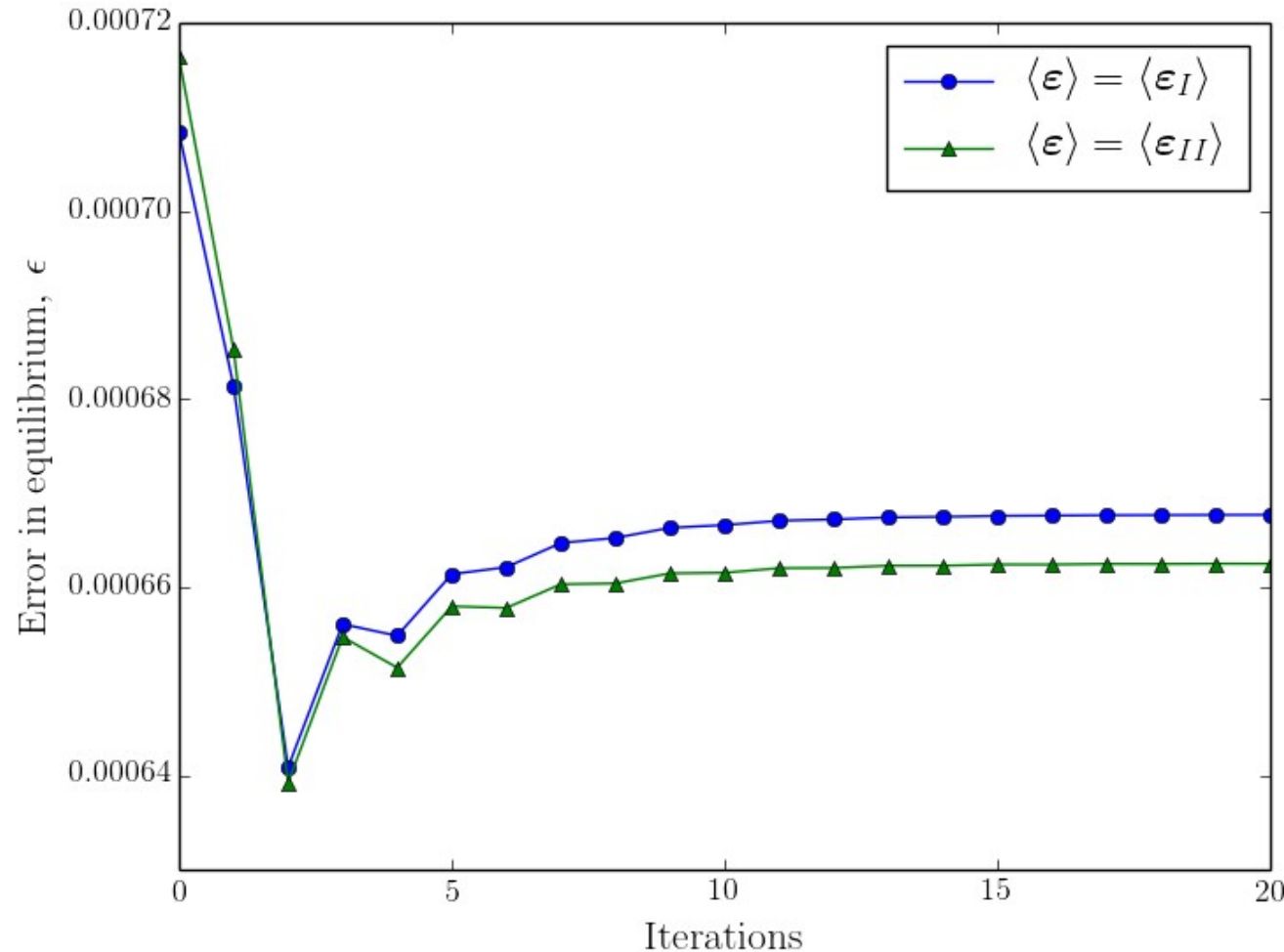
Error in equilibrium:

$${}^m\epsilon = \left[\frac{\langle \|\hat{\boldsymbol{\sigma}}^m(\underline{k}) \underline{k}\|^2 \rangle}{\hat{\boldsymbol{\sigma}}^m(\underline{0}) : \hat{\boldsymbol{\sigma}}^m(\underline{0})} \right]^{1/2}$$

- (1) Convergence depends on contrast between phases, and \mathbb{C}_0 .
- (2) Can not solve for infinite contrasts, i.e. rigid/compliant phases.
- (3) Numerical homogenization requires several numerical tests.

Convergence – Issues encountered

1) Increasing error vs number of iterations (also observed by Lebensohn, 2001).



$$N_x \times N_y = 2000 \times 2000$$

$$\mathbb{C}_0 = \langle \mathbb{C} \rangle$$

$$\langle \epsilon_I \rangle = 10^{-5} \underline{e}_1 \otimes \underline{e}_1$$

$$\langle \epsilon_{II} \rangle = 10^{-5} \underline{e}_2 \otimes \underline{e}_2$$

2) Some cases of instability, e.g. isotropic matrix-fiber w/ much stiffer fiber.

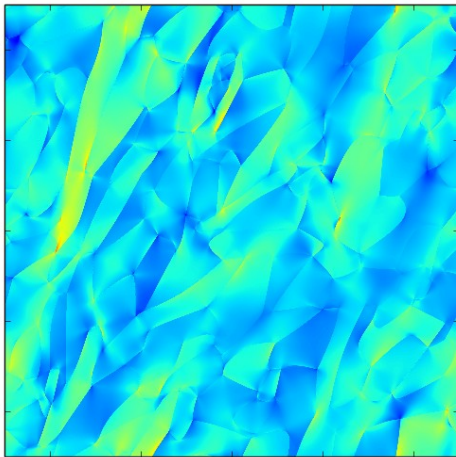
Numerical homogenization (strain-based)

We solve for $\tilde{\mathbb{C}}$ such that $\langle \boldsymbol{\sigma} \rangle = \tilde{\mathbb{C}} : \langle \boldsymbol{\varepsilon} \rangle$. From the Hill-Mandel principle, we have:

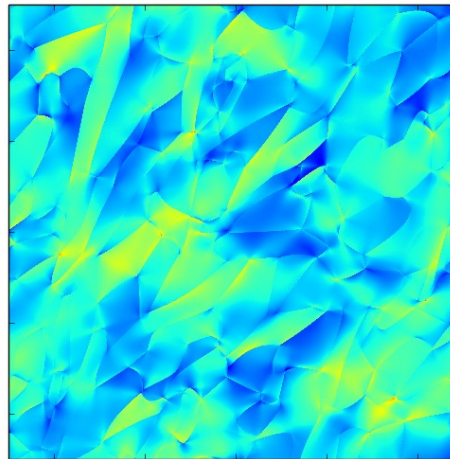
$$\begin{aligned} \langle \boldsymbol{\sigma} : \boldsymbol{\varepsilon} \rangle = & \tilde{C}_{1111} \langle \varepsilon_{11} \rangle^2 + \tilde{C}_{2222} \langle \varepsilon_{22} \rangle^2 + 4\tilde{C}_{1212} \langle \varepsilon_{12} \rangle^2 \\ & + 2\tilde{C}_{1122} \langle \varepsilon_{11} \rangle \langle \varepsilon_{22} \rangle + 4\tilde{C}_{1112} \langle \varepsilon_{11} \rangle \langle \varepsilon_{12} \rangle \\ & + 4\tilde{C}_{2212} \langle \varepsilon_{22} \rangle \langle \varepsilon_{12} \rangle \end{aligned}$$

Consider three mean-field loading cases:

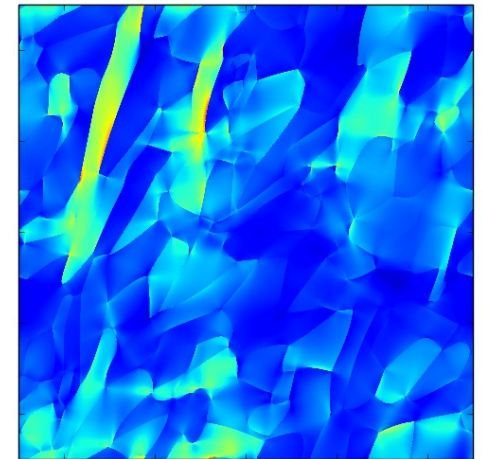
$$\langle \boldsymbol{\varepsilon}_I \rangle = \langle \varepsilon_{11} \rangle \underline{e}_1 \otimes \underline{e}_1 \quad \langle \boldsymbol{\varepsilon}_{II} \rangle = \langle \varepsilon_{22} \rangle \underline{e}_2 \otimes \underline{e}_2 \quad \langle \boldsymbol{\varepsilon}_{III} \rangle = \langle \varepsilon_{12} \rangle \underline{e}_1 \overset{s}{\otimes} \underline{e}_2$$



σ_I, ε_I



$\sigma_{II}, \varepsilon_{II}$



$\sigma_{III}, \varepsilon_{III}$

Numerical homogenization (strain-based)

Then, from these three loading cases, we have:

$$\tilde{C}_{1111} = \frac{\langle \boldsymbol{\sigma}_I : \boldsymbol{\varepsilon}_I \rangle}{\langle \varepsilon_{11} \rangle^2} \quad \tilde{C}_{2222} = \frac{\langle \boldsymbol{\sigma}_{II} : \boldsymbol{\varepsilon}_{II} \rangle}{\langle \varepsilon_{22} \rangle^2} \quad \tilde{C}_{1212} = \frac{\langle \boldsymbol{\sigma}_{III} : \boldsymbol{\varepsilon}_{III} \rangle}{4\langle \varepsilon_{12} \rangle^2}$$

Also, by superposition, we have:

$$\tilde{C}_{1122} = \frac{\langle (\boldsymbol{\sigma}_I + \boldsymbol{\sigma}_{II}) : (\boldsymbol{\varepsilon}_I + \boldsymbol{\varepsilon}_{II}) \rangle - \tilde{C}_{1111} \langle \varepsilon_{11} \rangle^2 - \tilde{C}_{2222} \langle \varepsilon_{22} \rangle^2}{2\langle \varepsilon_{11} \rangle \langle \varepsilon_{22} \rangle}$$

$$\tilde{C}_{1112} = \frac{\langle (\boldsymbol{\sigma}_I + \boldsymbol{\sigma}_{III}) : (\boldsymbol{\varepsilon}_I + \boldsymbol{\varepsilon}_{III}) \rangle - \tilde{C}_{1111} \langle \varepsilon_{11} \rangle^2 - 4\tilde{C}_{1212} \langle \varepsilon_{12} \rangle^2}{4\langle \varepsilon_{11} \rangle \langle \varepsilon_{12} \rangle}$$

$$\tilde{C}_{2212} = \frac{\langle (\boldsymbol{\sigma}_{II} + \boldsymbol{\sigma}_{III}) : (\boldsymbol{\varepsilon}_{II} + \boldsymbol{\varepsilon}_{III}) \rangle - \tilde{C}_{2222} \langle \varepsilon_{22} \rangle^2 - 4\tilde{C}_{1212} \langle \varepsilon_{12} \rangle^2}{4\langle \varepsilon_{22} \rangle \langle \varepsilon_{12} \rangle}$$

Moduli for elastic anisotropy

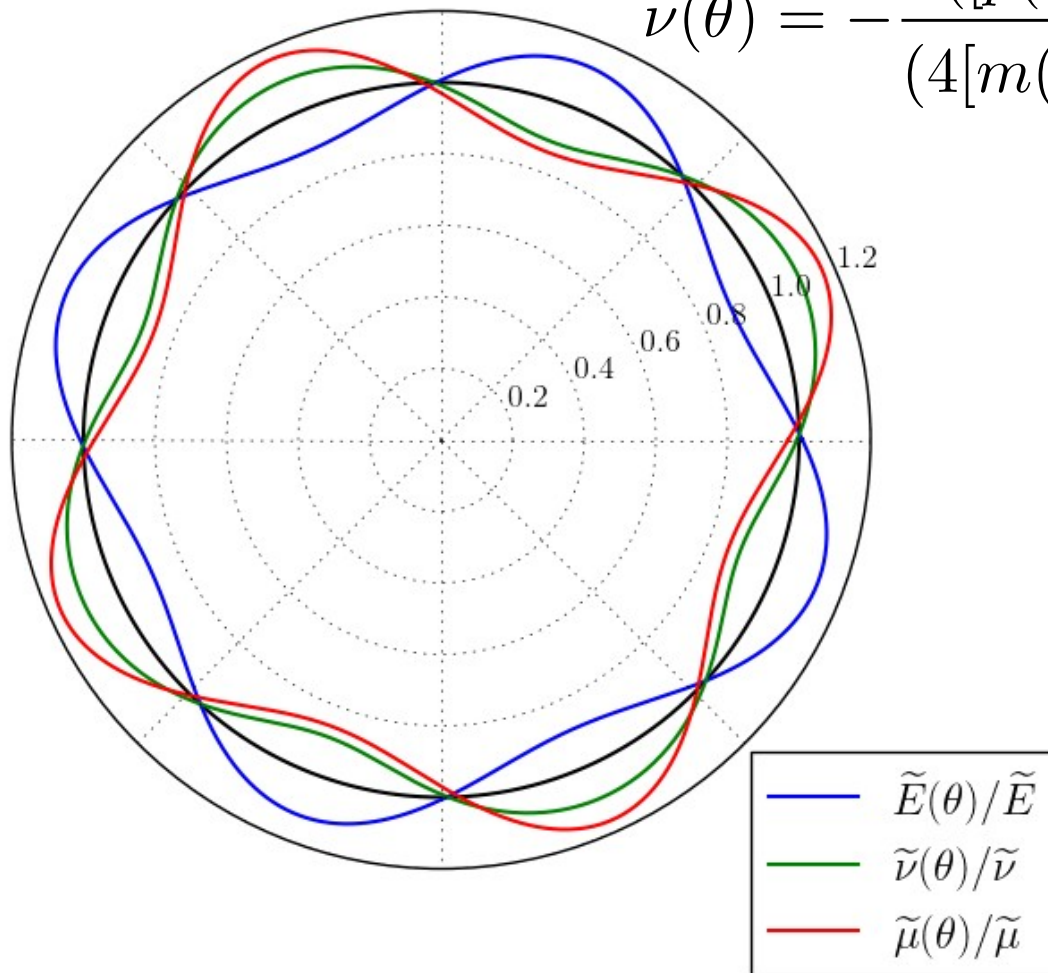
Following Hayes (1972), we have the following moduli:

$$\tilde{E}(\theta) = ([m(\theta) \otimes m(\theta)] : \tilde{\mathbb{C}}^{-1} : [m(\theta) \otimes m(\theta)])^{-1}$$

$$\tilde{\mu}(\theta) = (4[m(\theta) \otimes p(\theta)] : \tilde{\mathbb{C}}^{-1} : [m(\theta) \otimes p(\theta)])^{-1}$$

and Poisson's ratio:

$$\tilde{\nu}(\theta) = - \frac{([p(\theta) \otimes p(\theta)] : \tilde{\mathbb{C}}^{-1} : [m(\theta) \otimes m(\theta)])^{-1}}{(4[m(\theta) \otimes m(\theta)] : \tilde{\mathbb{C}}^{-1} : [m(\theta) \otimes m(\theta)])^{-1}}$$



$$\tilde{E} = \frac{1}{2\pi} \int_0^{2\pi} \tilde{E}(\theta) d\theta$$

$$\tilde{\mu} = \frac{1}{2\pi} \int_0^{2\pi} \tilde{\mu}(\theta) d\theta$$

$$\tilde{\nu} = \frac{1}{2\pi} \int_0^{2\pi} \tilde{\nu}(\theta) d\theta$$

Mean-field elastic self-consistent homogenization

The following interaction law is assumed between the overall mean strain state $\langle \boldsymbol{\varepsilon} \rangle$ and each local mean field $\langle \boldsymbol{\varepsilon} \rangle_\alpha$:

$$\langle \boldsymbol{\varepsilon} \rangle_\alpha = \hat{\mathbb{T}}_\alpha : \langle \boldsymbol{\varepsilon} \rangle$$

where $\hat{\mathbb{T}}_\alpha$ is a strain concentration tensor given by

$$\hat{\mathbb{T}}_\alpha = [\mathbb{I} + \hat{\mathbb{P}}^\alpha : (\mathbb{C}_\alpha - \hat{\mathbb{C}})]^{-1}$$

The Hill-polarization tensor $\hat{\mathbb{P}}_\alpha$ is computed after the assumption that Ω_α is idealized as an ellipsoid $\hat{\Omega}_\alpha$:

$$\hat{\mathbb{P}}^\alpha = \hat{\mathbb{P}}^\alpha(\underline{x}) = \int_{\hat{\Omega}_\alpha} \mathcal{F}^{-1} \left\{ \underline{\xi} \odot [\underline{\xi} \hat{\mathbb{C}} \underline{\xi}]^{-1} \odot \underline{\xi} \right\} (\underline{x} - \underline{y}) dV_{\underline{y}}$$

Computed after Masson (2008)

The apparent stiffness is solved for iteratively from:

$$\hat{\mathbb{C}} = \sum_{\alpha=1}^n c_\alpha \mathbb{C}_\alpha : \hat{\mathbb{T}}_\alpha$$

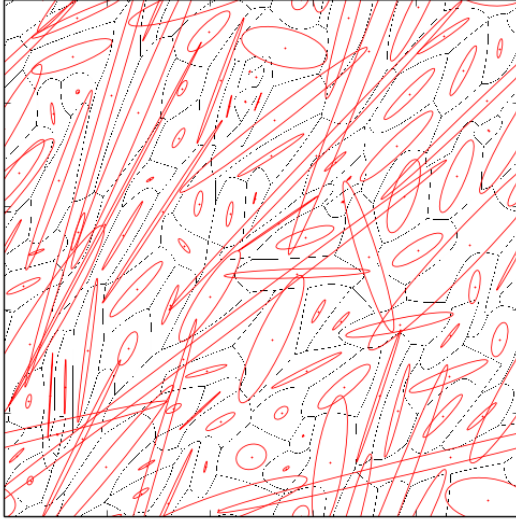
An arbitrary Ω_α can be idealized by many different ellipsoids $\hat{\Omega}_\alpha$.

What morphological idealization gives best estimates $\hat{\mathbb{C}}$?

Different morphological idealizations

From each characterization with 2nd order Minkowski tensors:

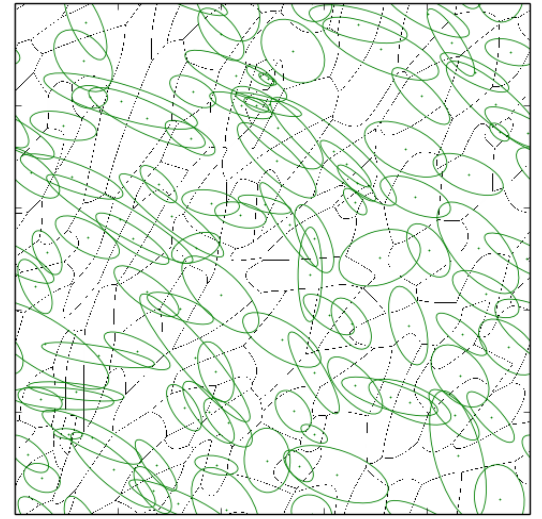
$$\mathbf{W}_0^{2,0}$$



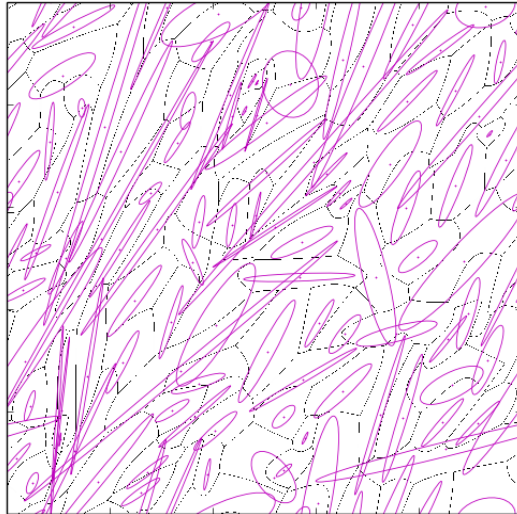
$$\mathbf{W}_1^{2,0}$$



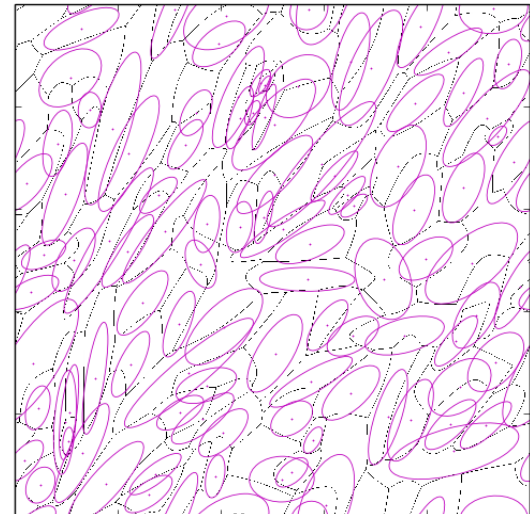
$$\mathbf{W}_1^{0,2}$$



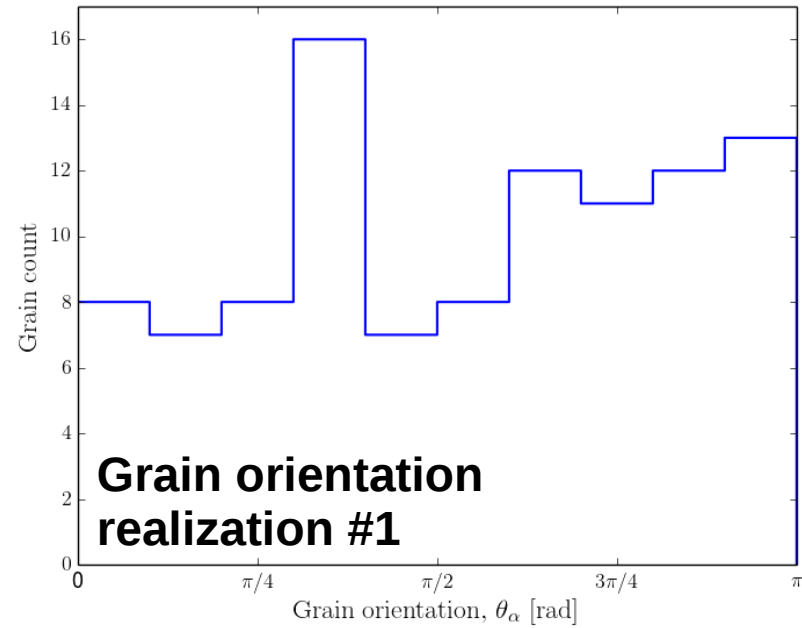
$$\mathbf{W}_2^{2,0}$$



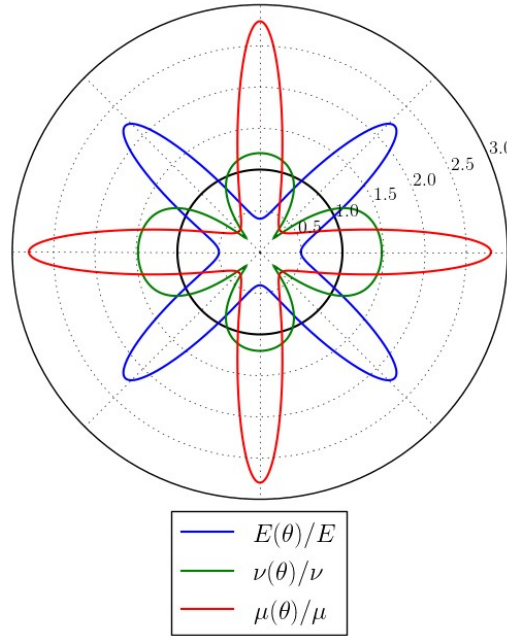
$$\mathbf{W}_2^{1,1}$$



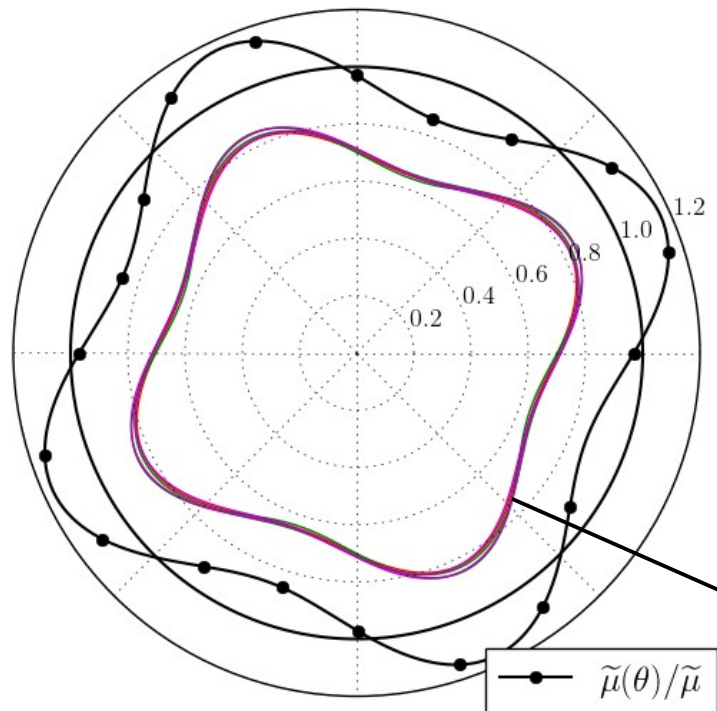
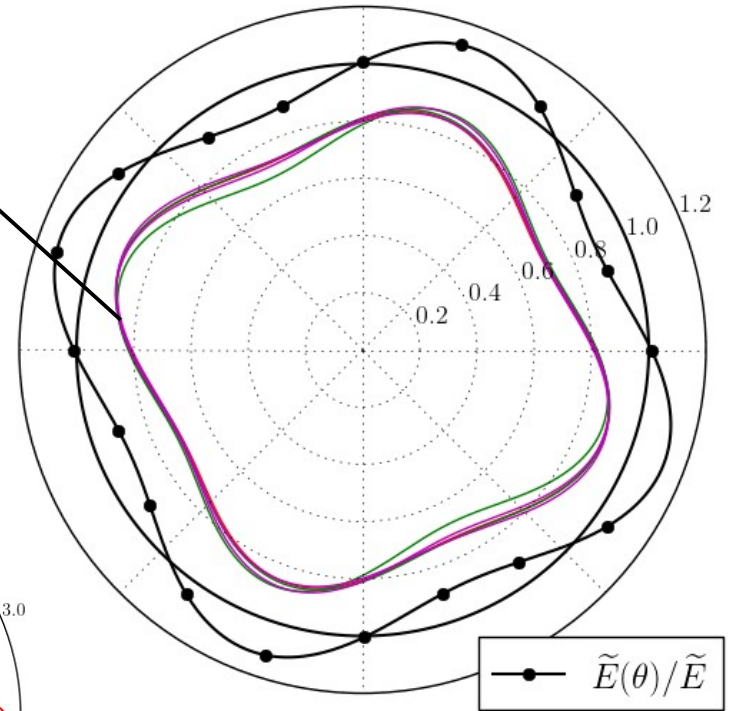
Comparison of SC-based elastic stiffness estimates



local grain
stiffness

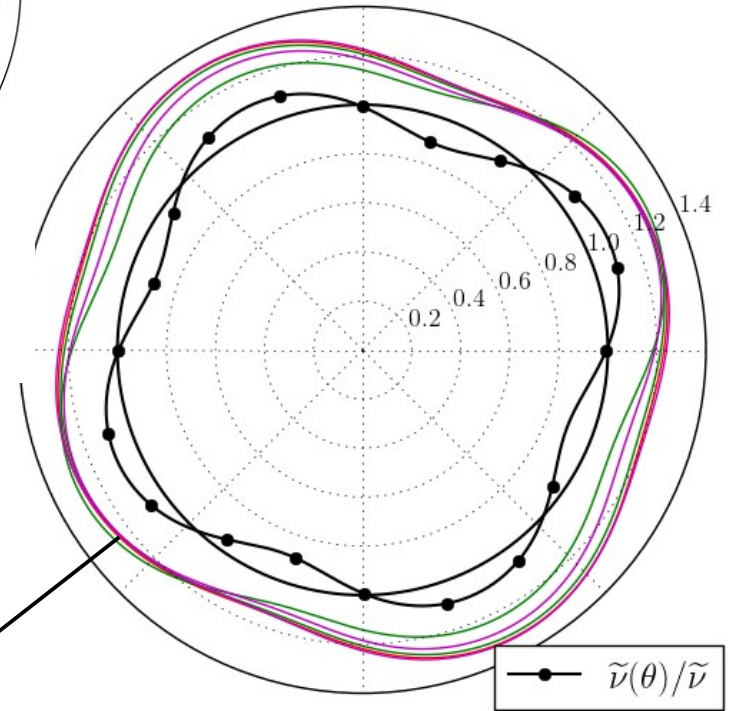


$$\hat{E}_\nu^{r,s}(\theta)/\tilde{E}$$

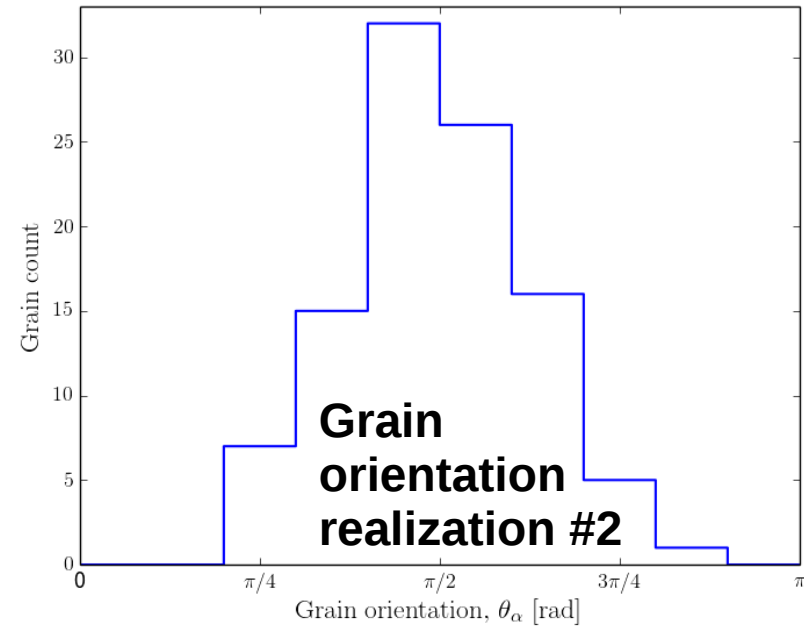


$$\hat{\mu}_\nu^{r,s}(\theta)/\tilde{\mu}$$

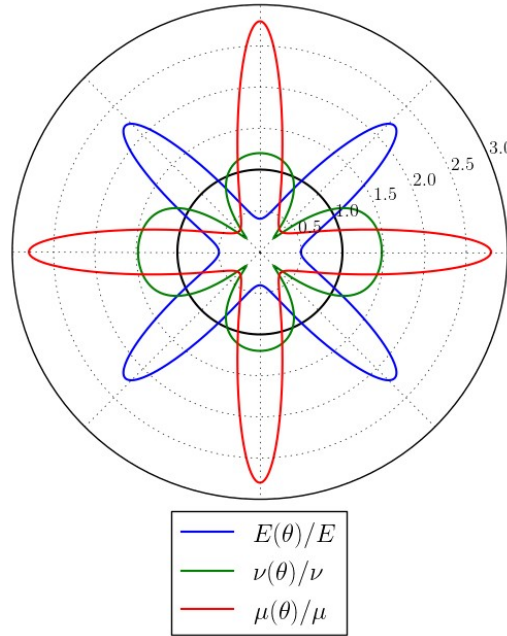
$$\hat{\nu}_\nu^{r,s}(\theta)/\tilde{\nu}$$



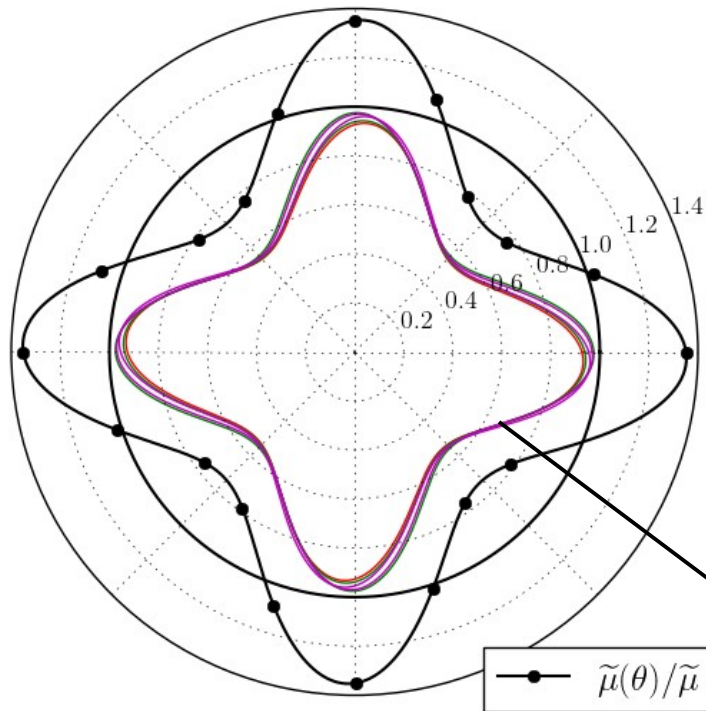
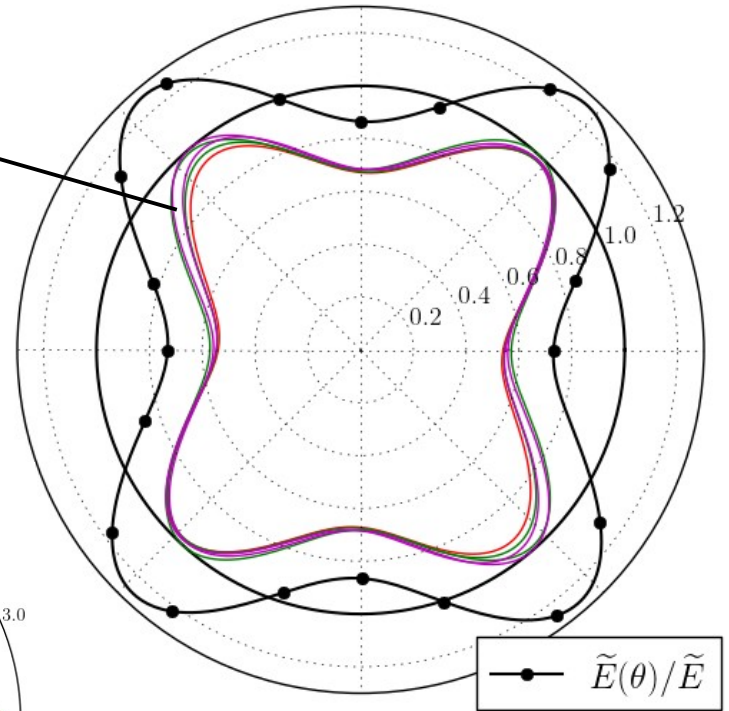
Comparison of SC-based elastic stiffness estimates



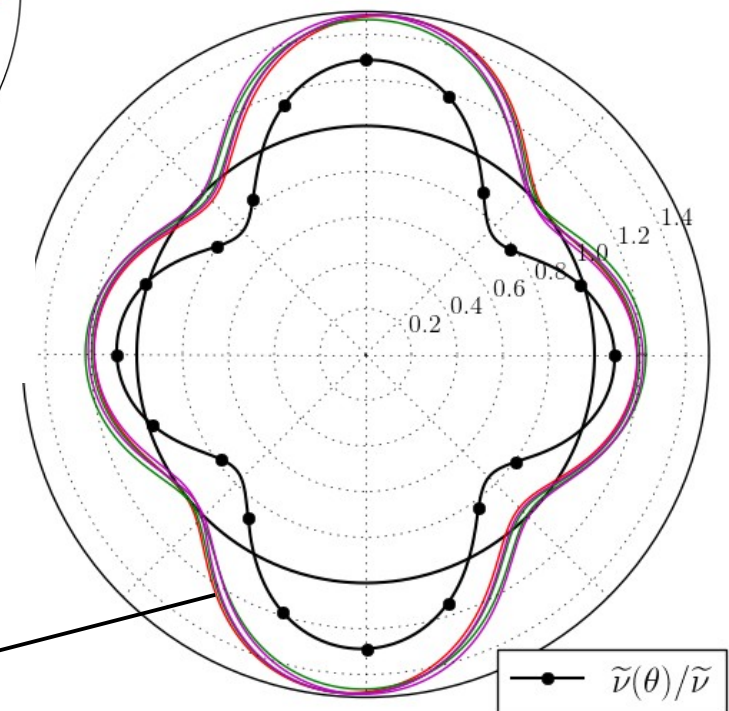
local grain stiffness



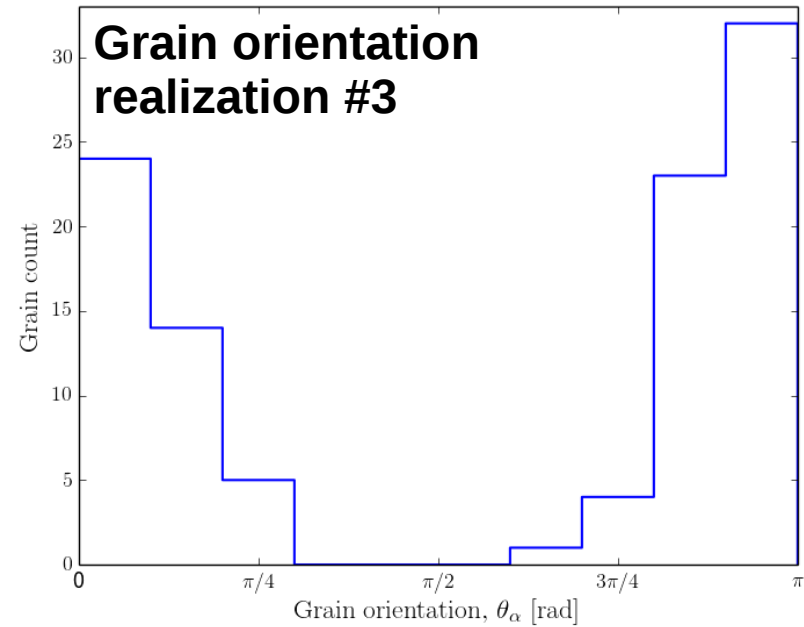
$$\hat{E}_\nu^{r,s}(\theta)/\tilde{E}$$



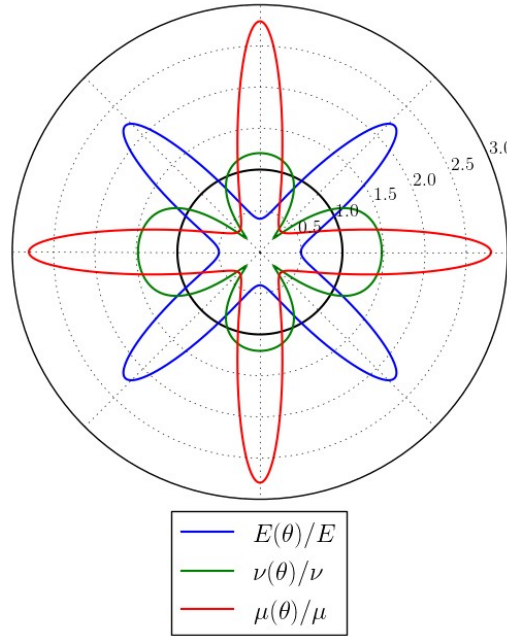
$$\hat{\nu}_\nu^{r,s}(\theta)/\tilde{\nu}$$



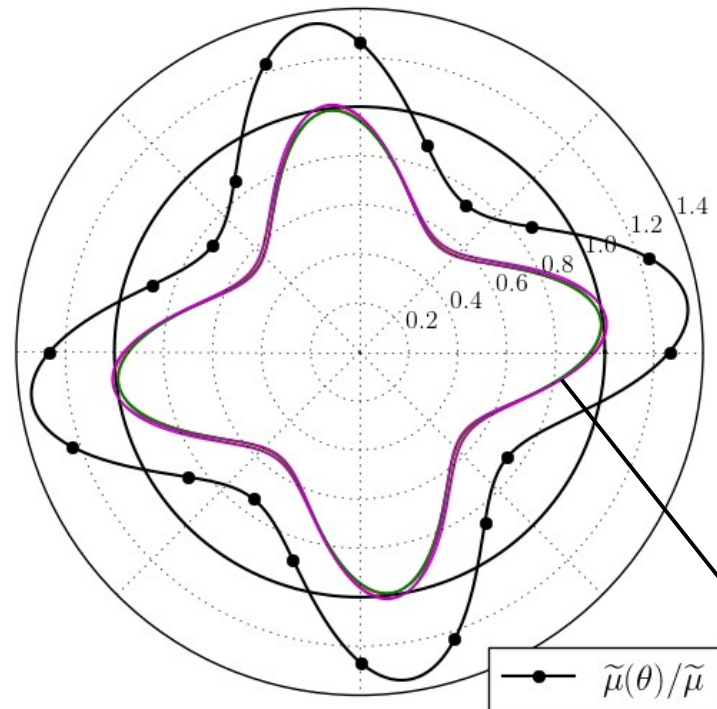
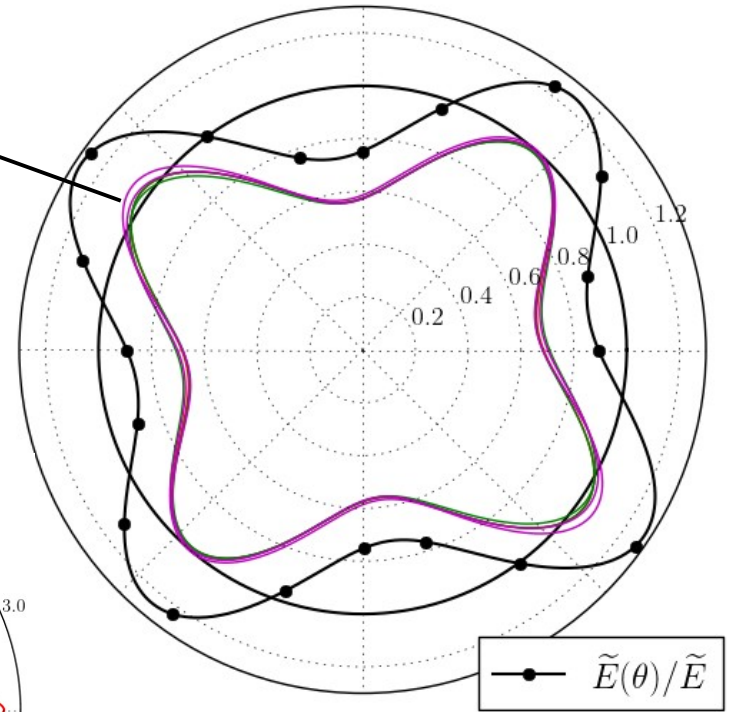
Comparison of SC-based elastic stiffness estimates



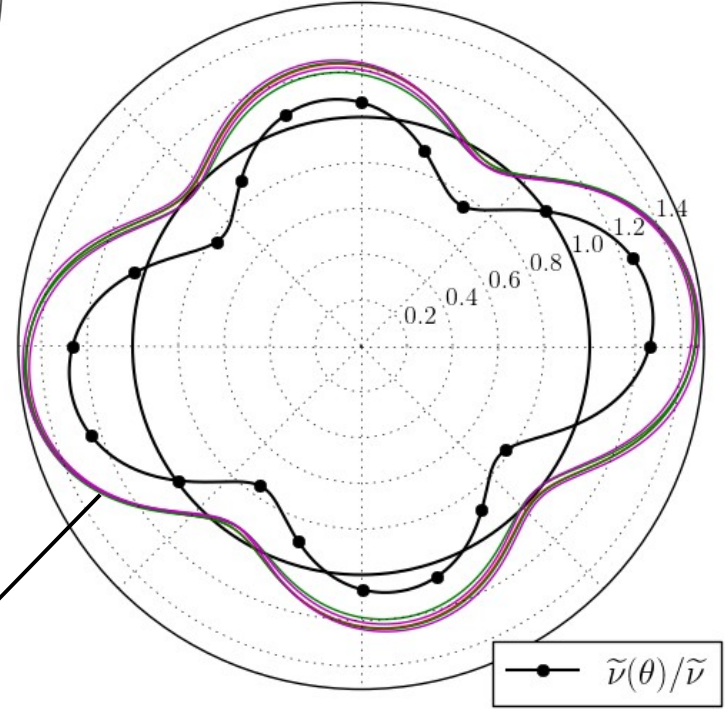
local grain stiffness



$$\hat{E}_\nu^{r,s}(\theta)/\tilde{E}$$



$$\hat{\nu}_\nu^{r,s}(\theta)/\tilde{\nu}$$



Conclusion

- Morphological characterization of single grains
- Numerical homogenization
- Self-consistent homogenization
- Shape idealization
- Comparison of SC estimates of elastic stiffness

References

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