

Preconditioners based on Voronoi quantizers of random coefficient fields for the iterative solves of stochastic elliptic partial differential equations

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SECURE CONNECTIONS
FOR A SMARTER WORLD

Stochastic elliptic partial differential equations (PDEs)

► Let us consider the domain $\Omega := [0, 1]^2$ with boundary $\partial\Omega$, and the set Θ of all possible outcomes. We search for $u : \bar{\Omega} \times \Theta \rightarrow \mathbb{R}$ such that

$$\begin{aligned}\nabla \cdot [\kappa(x, \theta) \nabla u(x, \theta)] &= f(x) \quad \forall x \in \Omega \\ u(x, \theta) &= 0 \quad \forall x \in \partial\Omega\end{aligned}$$

is almost surely satisfied.

► We assume $f : \Omega \rightarrow \mathbb{R}$ is square integrable, i.e., $f \in L^2(\Omega)$ where

$$\|f\|_{\Omega}^2 := \int_{\Omega} |f(x)|^2 dx < \infty \iff f \in L^2(\Omega).$$

► We further assume the random coefficient field $\kappa : \Omega \times \Theta \rightarrow \mathbb{R}$ is such that $P[\theta \in \Theta : \kappa(\cdot, \theta) \in \mathcal{A}] = 1$ where $\mathcal{A} := \{\kappa \in L^2(\Omega), \kappa(x) > 0 \quad \forall x \in \Omega\}$.

► We define the set $L^2(\Omega, \Theta)$ of 2nd order stochastic processes such that

$$\mathbb{E}[\|\kappa(\cdot, \theta)\|_{\Omega}^2] < \infty \iff \kappa \in L^2(\Omega, \Theta).$$

► See Babuska al. (2004) for more details on existence and uniqueness of u .

Babuska, Ivo, Raúl Tempone, and Georgios E. Zouraris. "Galerkin finite element approximations of stochastic elliptic partial differential equations." SIAM Journal on Numerical Analysis 42.2 (2004): 800-825.

Karhunen-Loève (KL) representation of coefficient fields

- ▶ Let κ be a real-valued 2nd order stochastic processes, i.e., $\kappa \in L^2(\Omega, \Theta)$, with zero mean and known covariance $C(x, x') = \mathbb{E}[\kappa(x, \cdot)\kappa(x', \cdot)]$.
- ▶ Then, the truncated KL expansion κ_N of κ minimizes the representation error $\mathbb{E}[\|\kappa - \kappa_N\|_\Omega^2]$ over N -dimensional function spaces. It is given by

$$\kappa_N(x, \theta) := \sum_{\alpha=1}^N \sqrt{\lambda_\alpha} \xi_\alpha(\theta) \Phi_\alpha(x)$$

where $(\lambda_\alpha, \Phi_\alpha) \in \mathbb{R}^+ \times L^2(\Omega)$ is the α -th dominant eigen-pair of the covariance function and Φ_α is a normalized eigenfunction. That is, $(\lambda_\alpha, \Phi_\alpha)$ is solution of the Fredholm integral equation:

$$\int_{\Omega} C(x, x') \Phi(x') dx' = \lambda \Phi(x), \quad \|\Phi\|_{\Omega}^2 = 1.$$

- ▶ The random variables (RVs) ξ_α , a.k.a. the "stochastic coordinates" of κ_N , are uncorrelated with zero mean and unit variance, i.e., $\mathbb{E}[\xi_\alpha \xi_\beta] = \delta_{\alpha\beta}$.
- ▶ In case κ is a Gaussian process, the RVs are independent.

State-of-the-art

Two main approaches have been used to characterize the uncertainty of u .

► Approaches based on **polynomial chaos (PC)** expansions:

Leveraging the KL expansion, an approximate functional representation of the random solution $u : \Omega \times \Theta \rightarrow \mathbb{R}$ is built in the form of a spectral expansion

$$u_M(x, \boldsymbol{\xi}(\theta)) := \sum_{\alpha=0}^M u_{\alpha}(x) \Psi_{\alpha}(\boldsymbol{\xi}(\theta))$$

where $\Psi_{\alpha} : \Theta \rightarrow \mathbb{R}$ is set a priori from a finite polynomial basis. The computation of the coefficients $u_{\alpha} : \Omega \rightarrow \mathbb{R}$ is done by stochastic Galerkin, regression or collocation. Once equipped with a spectral expansion, statistics can be computed on the basis of approximate solution realizations.

► Approaches based on **Monte Carlo (MC)** sampling:

Statistics are computed on the basis of solution realizations $u(\cdot, \theta)$ which are obtained by solving a deterministic equations with the corresponding realizations $\kappa(\cdot, \theta) \in \mathcal{A}$ of the coefficient field. The spatial discretization of the deterministic equation for a given event θ leads to an SPD linear system

$$\mathbf{A}(\theta)\mathbf{u}(\theta) = \mathbf{b}(\theta).$$



Limit preconditioning strategies

- $\mathbf{A}(\theta)$ being SPD, $\mathbf{A}(\theta)\mathbf{u}(\theta) = \mathbf{b}(\theta)$ can be solved by conjugate gradient (CG), i.e., we search for iterates $\mathbf{u}^{(j)}(\theta)$ such that:

$$\begin{aligned}\mathbf{u}^{(j)}(\theta) - \mathbf{u}^{(0)} &\in \mathcal{K}^{(j)}(\mathbf{A}(\theta), \mathbf{r}^{(0)}(\theta)) \\ \mathbf{r}^{(j)}(\theta) &\perp \mathcal{K}^{(j)}(\mathbf{A}(\theta), \mathbf{r}^{(0)}(\theta))\end{aligned}$$

where $\mathcal{K}^{(j)}(\mathbf{A}(\theta), \mathbf{r}^{(0)}(\theta)) := \text{Span}\{\mathbf{r}^{(0)}(\theta), \mathbf{A}(\theta)\mathbf{r}^{(0)}(\theta), \dots, \mathbf{A}^{j-1}(\theta)\mathbf{r}^{(0)}(\theta)\}$ is the Krylov subspace of $\mathbf{A}(\theta)$ generated by $\mathbf{r}^{(0)}(\theta)$.

- J is the (random) number of solver iterations to reach a backward error of 10^{-6} .

Median realization preconditioner

A single SPD preconditioner $\mathbf{M}_{0,\bullet}^{-1}$ is defined based on $\mathbf{A}(\xi = 0)$. We then search for iterates $\mathbf{u}^{(i)}(\theta)$ such that:

$$\begin{aligned}\mathbf{u}^{(j)}(\theta) - \mathbf{u}^{(0)} &\in \mathcal{K}^{(j)}(\mathbf{M}_{0,\bullet}^{-1}\mathbf{A}(\theta), \mathbf{M}_{0,\bullet}^{-1}\mathbf{r}^{(0)}(\theta)) \\ \mathbf{r}^{(j)}(\theta) &\perp \mathcal{K}^{(j)}(\mathbf{M}_{0,\bullet}^{-1}\mathbf{A}(\theta), \mathbf{M}_{0,\bullet}^{-1}\mathbf{r}^{(0)}(\theta))\end{aligned}$$

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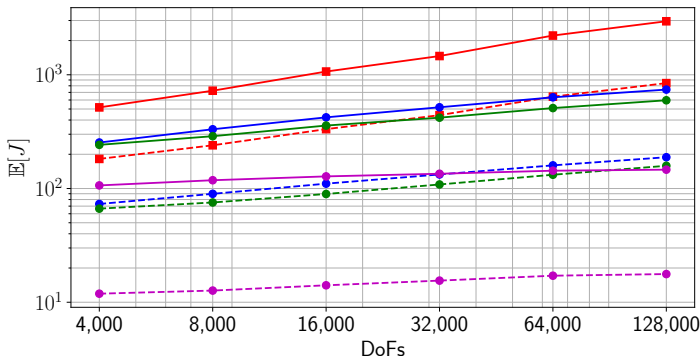
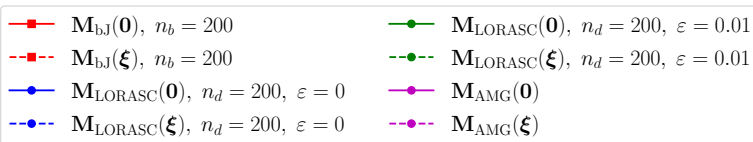
Realization-dependent ideal preconditioner

For every single realization θ , a preconditioner $\mathbf{M}_{\bullet}^{-1}(\theta)$ is defined based on $\mathbf{A}(\theta)$. We then search for iterates $\mathbf{u}^{(i)}(\theta)$ such that:

$$\begin{aligned}\mathbf{u}^{(j)}(\theta) - \mathbf{u}^{(0)} &\in \mathcal{K}^{(j)}(\mathbf{M}_{\bullet}^{-1}(\theta)\mathbf{A}(\theta), \mathbf{M}_{\bullet}^{-1}(\theta)\mathbf{r}^{(0)}(\theta)) \\ \mathbf{r}^{(j)}(\theta) &\perp \mathcal{K}^{(j)}(\mathbf{M}_{\bullet}^{-1}(\theta)\mathbf{A}(\theta), \mathbf{M}_{\bullet}^{-1}(\theta)\mathbf{r}^{(0)}(\theta))\end{aligned}$$

Results of limit preconditioning strategies

► We consider a covariance $C(x, x') = \exp(-\|x - x'\|^2/0.1^2)$.



► Speedup of $\text{M}_{\bullet}^{-1}(\xi)$: 2-3X (bJ), 3X (LORASC), 10X (AMG).

Alternative preconditioning strategies

- ▶ Using $\mathbf{M}_\bullet(\mathbf{0})$ leads to large numbers of solver iterations, while $\mathbf{M}_\bullet(\boldsymbol{\xi})$ entails significant preconditioner setup times, e.g., computing factorizations for every single realization $\boldsymbol{\xi}(\theta)$.
- ▶ Alternative preconditioning strategies are needed.
- ▶ We consider preconditioning strategies which consist of both:
 - 1 A P -quantizer $q : \kappa \in \mathcal{A} \mapsto \hat{\kappa} \in \hat{\mathcal{A}}$ with centroidal coefficient fields in the codebook $\hat{\mathcal{A}} := \{\hat{\kappa}_p \in \mathcal{A}, p = 1, \dots, P\}$. The quantizer q serves as a compact representation of the random coefficient field.
 - 2 A preconditioner $\mathbf{M} : \kappa \in \mathcal{A} \mapsto \mathbf{M}(\kappa) \in \text{Sym}_{n \times n}^+(\mathbb{R})$.
We are interested in the composition $\mathbf{M} \circ q : \kappa \in \mathcal{A} \mapsto \{\hat{\mathbf{M}}_1, \dots, \hat{\mathbf{M}}_P\}$.
The preconditioners $\hat{\mathbf{M}}_1, \dots, \hat{\mathbf{M}}_P$ are not known explicitly.
Instead, as we consider solving cycles of algebraic multigrid solvers for $\mathbf{A}(\hat{\kappa}_1), \dots, \mathbf{A}(\hat{\kappa}_P)$, we simply know how to efficiently compute the mapping $\mathbf{x} \mapsto \hat{\mathbf{M}}_p^{-1} \mathbf{x}$ for $p = 1, \dots, P$.

Alternative preconditioning strategies

- We assume there exists an invertible map $T_1 : L^2(\Omega) \rightarrow L^2(\Omega)$ such that $T_1^{-1}\kappa$ is a Gaussian process with zero mean.
- We know the truncated KL expansion $\hat{T}_1^{-1}\kappa$ which approximates $T_1^{-1}\kappa$ with m dominant eigen-pairs $(\lambda_\alpha, \Phi_\alpha) \in \mathbb{R}^+ \times L^2(\Omega)$.
- Let us introduce the following projection:

$$\hat{P}_1^{-1} : f \in L^2(\Omega) \mapsto \begin{bmatrix} \lambda_1^{-1/2} \langle \Phi_1, f \rangle_\Omega \\ \vdots \\ \lambda_m^{-1/2} \langle \Phi_m, f \rangle_\Omega \end{bmatrix}, \langle f, g \rangle_\Omega := \int_\Omega f(x)g(x)dx \quad \forall f, g \in L^2(\Omega)$$

and $\hat{P}_1 : \boldsymbol{\xi} \in \mathbb{R}^m \mapsto \sum_{k=1}^m \lambda_k^{1/2} \xi_k \Phi_k(\cdot) \in L^2(\Omega)$ s.t. $\hat{T}_1^{-1} = \hat{P}_1 \circ \hat{P}_1^{-1} \circ T_1^{-1}$.

- We introduce a quantizer q_2 of \mathbb{R}^m and an invertible map $T_2 : \mathbb{R}^m \rightarrow \mathbb{R}^m$ which we use as follows to define q :

$$q : \kappa(\cdot) \in \mathcal{A} \mapsto \tilde{T}(q_2(\tilde{T}^{-1}\kappa(\cdot))) \in \hat{\mathcal{A}} \subset \mathcal{A}$$

where $\tilde{T} := T_1 \circ \hat{P}_1 \circ T_2$ and $\hat{\mathcal{A}}$ is the codebook induced by q .

Optimal preconditioning strategies

- The representation error of $\kappa(\cdot, \Theta)$ by $q(\kappa(\cdot, \Theta))$ is the distortion

$$w(q, d) := \mathbb{E}[d(\kappa, q(\kappa))] = \int_{\Theta} d(\kappa(\cdot, \theta), q(\kappa(\cdot, \theta))) d\mu(\theta)$$

where the distortion functional, a.k.a. divergence, $d : \mathcal{A} \times \mathcal{A} \rightarrow [0, \infty)$ measures proximity between realizations of the coefficient field.

- Every Voronoi quantizer q has a codebook $\hat{\mathcal{A}} := \{\hat{\kappa}_1, \dots, \hat{\kappa}_P\} \subset \mathcal{A}$ s.t.

$$q : \kappa \in \mathcal{A} \mapsto \sum_{p=1}^P \hat{\kappa}_p \mathbf{1}[\kappa \in \mathcal{A}_p], \quad \mathcal{A}_p \subset \{\kappa \in \mathcal{A}, d(\kappa, \hat{\kappa}_p) \leq d(\kappa, \hat{\kappa}_q), q = [1, P]\}$$

and so that $\mathcal{A}_1, \dots, \mathcal{A}_P$ form a Borel partition of \mathcal{A} .

- The local distortions $w_p(q, d) := \mathbb{E}[d(\kappa, q(\kappa)) \mid \kappa \in \mathcal{A}_p] = w_p(\hat{\kappa}_p, d)$ and attribution frequencies $f_p := \mu(\mathcal{A}_p)$ form a decomposition of distortion

$$w(\hat{\mathcal{A}}, d) = \sum_{p=1}^P f_p w_p(\hat{\kappa}_p, d).$$

- For a partition $\mathcal{A}_1, \dots, \mathcal{A}_P$, the distortion is minimized by selecting centroidal fields $\hat{\kappa}_p$ which minimize the local distortions $w_p(\hat{\kappa}_p, d)$.



Computation of stationary quantizers

► Remember that we let $q(\kappa(\cdot)) = \tilde{T}(q_2(\tilde{T}^{-1}\kappa(\cdot)))$ be induced by a vector quantizer q_2 of $T_2^{-1}(\xi)$.

► We are interested in L^2 quantizers with distortions given by

$$w_2(q_2) := \mathbb{E}[\|T_2^{-1}(\xi) - q_2(T_2^{-1}(\xi))\|^2] = \int_{\Theta} \|T_2^{-1}(\xi) - q_2(T_2^{-1}(\xi))\|^2 d\mu_{\xi}(\theta).$$

► We let q_2 be a Voronoi quantizer, and we denote the partition of $T_2^{-1}(\mathbb{R}^m)$ induced by q_2 as $\mathcal{H}_1, \dots, \mathcal{H}_P$ so that

$$q_2(T_2^{-1}(\xi)) := \sum_{p=1}^P \hat{\eta}_p \mathbf{1}[T_2^{-1}(\xi) \in \mathcal{H}_p]$$

where $\hat{\eta}_p := T_2^{-1}(\hat{\xi}_p)$.

► The distortion of q_2 admits the following decomposition:

$$w_2(q_2) = \sum_{p=1}^P w_{2,p}(q_2) \mu_{\xi}(T_2^{-1}(\mathcal{H}_p))$$

where $w_{2,p}(q_2) := \mathbb{E}[\|T_2^{-1}(\xi) - q_2(T_2^{-1}(\xi))\|^2 \mid T_2^{-1}(\xi) \in \mathcal{H}_p]$.



Computation of stationary quantizers

- ▶ The computation of $\mu_{\xi}(T_2^{-1}(\mathcal{H}_p))$ and $w_{2,p}(q_2)$ is intractable.
- ▶ In practice, we use an empirical measure of distortion. Given an n_s -sample $\kappa_1, \dots, \kappa_{n_s}$ of i.i.d. realizations of the coefficient field, we compute $\xi_s := \hat{P}_1^{-1}(T_1^{-1}\kappa_s)$ for $s = 1, \dots, n_s$ and approximate $w_2(q_2)$ with

$$w_2^{(n_s)}(q_2) := \frac{1}{n_s} \sum_{s=1}^{n_s} \|T_2^{-1}(\xi_s) - q_2(T_2^{-1}(\xi_s))\|^2$$

which is also given by

$$w_2^{(n_s)}(q_2) = \sum_{p=1}^P f_{2,p}^{(n_s)} w_{2,p}^{(n_s)}(q_2) \quad \text{where} \quad f_{2,p}^{(n_s)} := \frac{1}{n_s} \sum_{s=1}^{n_s} \mathbf{1}[T_2^{-1}(\xi_s) \in \mathcal{H}_p]$$

is the empirical measure of \mathcal{H}_p associated with ξ_1, \dots, ξ_{n_s} , and

$$w_{2,p}^{(n_s)}(q_2) := \frac{1}{f_{2,p}^{(n_s)} n_s} \sum_{s=1}^{n_s} \|T_2^{-1}(\xi_s) - q_2(T_2^{-1}(\xi_s))\|^2 \mathbf{1}[T_2^{-1}(\xi_s) \in \mathcal{H}_p].$$

- ▶ Several algorithms compute stationary quantizers q_2 on the basis of these empirical measures, e.g., k -means, competitive learning vector quantization (CLVQ), ...

Choices of the map $T_2(\xi)$

- Upon defining the map $T_2 : \mathbb{R}^m \rightarrow \mathbb{R}^m$, we introduce some control over the design of q_2 and its underlying codebook, as well as of q .
- First, we aim to define T_2 so as to minimize the $L^2(\Omega)$ -distortion of $\hat{T}_1^{-1}\kappa$. By orthonormality of the eigenfunctions of the KL expansion, we have:

$$\|\hat{T}_1^{-1}\kappa(\cdot, \theta)\|_{\Omega}^2 = \left\| \sum_{k=1}^m \lambda_k^{1/2} \Phi_k(x) \xi_k(\theta) \right\|_{\Omega}^2 = \sum_{k=1}^m \lambda_k \xi_k(\theta)^2 = \boldsymbol{\xi}(\theta)^T \boldsymbol{\Lambda} \boldsymbol{\xi}(\theta)$$

which can be recast as $\|\boldsymbol{\Lambda}^{1/2} \boldsymbol{\xi}(\theta)\|^2$ for all $\theta \in \Theta$. Consequently, the map $T_2^{-1} : \boldsymbol{\chi} \mapsto \boldsymbol{\Lambda}^{1/2} \boldsymbol{\chi}$ is such that $\|T_2^{-1} \boldsymbol{\xi}(\theta)\|^2 = \|\hat{T}_1^{-1}\kappa(\cdot, \theta)\|_{\Omega}^2$.

- Second, we aim at designing stationary quantizers with constant frequencies. We consider

$$T_2^{-1} : \boldsymbol{\chi} \mapsto \boldsymbol{\Lambda}^{1/2} F_{\xi} \circ \boldsymbol{\chi} \quad \text{where} \quad F_{\xi} \circ \boldsymbol{\chi} = \begin{bmatrix} F_{\xi}(\chi_1) \\ \vdots \\ F_{\xi}(\chi_m) \end{bmatrix}$$

where $F_{\xi}(\chi) = \Pr[\xi \leq \chi]$. Our experiments show that this choice of T_2^{-1} yields stationary quantizers q_2 with $f_1 \approx \dots \approx f_P$.

Quantizations based on deterministic grids

- We want a quantizer for which the number m of KL modes considered depends on the number P of preconditioners.
- To indicate the number m of KL modes in the quantization, we write $q_2^{(m)}$.
- For $m = 1$, we use
$$q_2^{(1)}(\xi) = T_2^{-1}(0)\mathbf{1}[-s/2 \leq \xi < s/2] + T_2^{-1}(-s)\mathbf{1}[\xi < s/2] + T_2^{-1}(s)\mathbf{1}[s/2 \leq \xi]$$
so as to provide symmetric design. Moreover, in order to have constant attribution frequencies, we let $s = 2F_\xi^{-1}(2/3) \approx 0.8614$.
- For higher numbers m of KL modes, we have

$$q_2^{(m)}(\xi) = \sum_{p=0}^{2^m} T_2^{-1}(\hat{\xi}_p)\mathbf{1}[T_2^{-1}(\xi) \in \mathcal{H}_p]$$

where $\mathcal{H}_0, \dots, \mathcal{H}_{2^m}$ form a Voronoi partition of $T_2^{-1}(\mathbb{R}^m)$ and are given such that

$$\mathcal{H}_p \subset \left\{ T_2^{-1}(\xi), \xi \in \mathbb{R}^m, \|\xi - \hat{\xi}_p\| \leq \|\xi - \hat{\xi}_q\|, q = 0, \dots, 2^m \right\}$$

with centers $\hat{\xi}_0, \dots, \hat{\xi}_{2^m}$.

Quantizations based on deterministic grids

Algorithm 1 GetGridCoordinates(s, m)

Require: Grid parameter s ,

Number of KL modes m

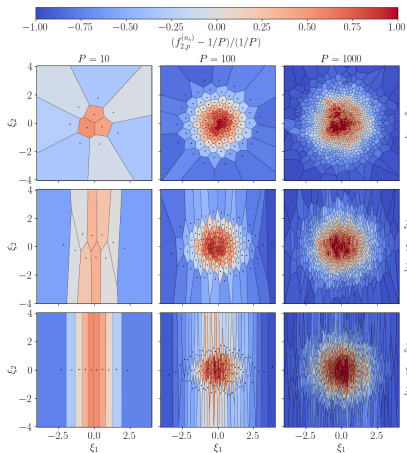
Ensure: Centroids $T_2^{-1}(\hat{\xi}_0), \dots, T_2^{-1}(\hat{\xi}_{2^m})$ of quantizer $q_2^{(m)}$.

```
1:  $\hat{\xi}_0 := \mathbf{0}$ 
2:  $p := 1$ 
3: for  $\hat{\xi}_{p,1} \in (-s, s)$  do
4:   for  $\hat{\xi}_{p,2} \in (-s, s)$  do
5:      $\vdots$ 
6:   for  $\hat{\xi}_{p,m} \in (-s, s)$  do
7:      $\hat{\xi}_p := [\hat{\xi}_{p,1}, \dots, \hat{\xi}_{p,m}]^T$ 
8:      $p := p + 1$ 
9:   end for
10: end for
11: end for
12: return  $T_2^{-1}(\hat{\xi}_0), \dots, T_2^{-1}(\hat{\xi}_{2^m})$ 
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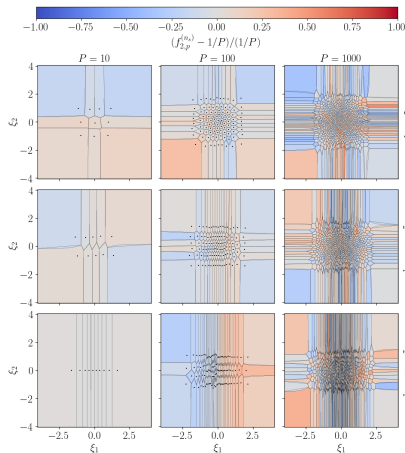
Attribution frequencies for different stationary quantizers

Let $m = 2$ and $\xi \sim \mathcal{N}(\mathbf{0}, \mathbf{I}_2)$. We compute stationary quantizers q_2 of \mathbb{R}^2 with different T_2 .

$$T_2^{-1}(\xi) = \Lambda^{1/2} \xi$$

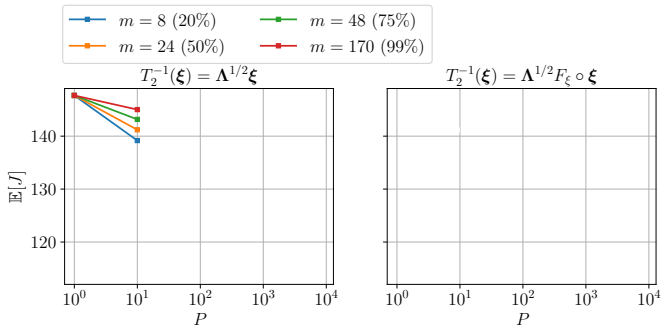


$$T_2^{-1}(\xi) = \Lambda^{1/2} F_\xi \circ \xi$$



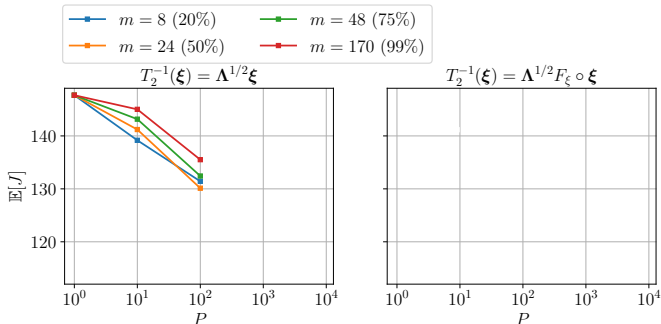
Effect of preconditioning strategies from different stationary quantizers and deterministic grids

- Let $T_1^{-1}\kappa := \log \kappa$ be a Gaussian process with $C(x, x') = \exp\left(\frac{-\|x-x'\|^2}{0.1^2}\right)$
- $\mathbb{E}[J]$ is estimated with 100,000 realizations and \mathbf{A} is 100,000-dimensional.



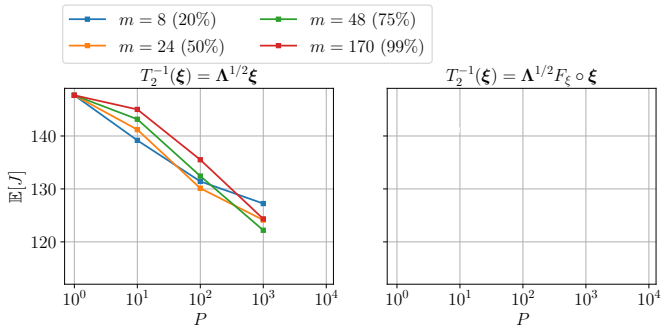
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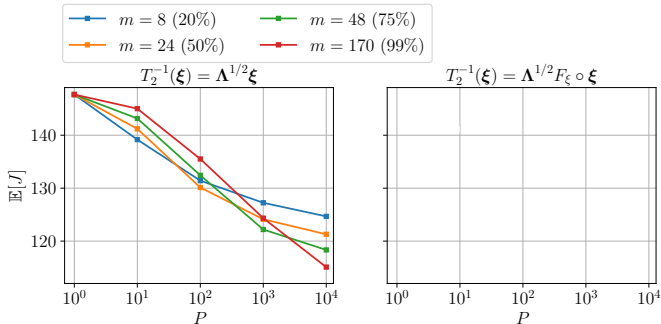
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- For some m , $\mathbb{E}[J]$ stagnates passed some value of P . The smaller m the faster it happens.

Effect of preconditioning strategies from different stationary quantizers and deterministic grids

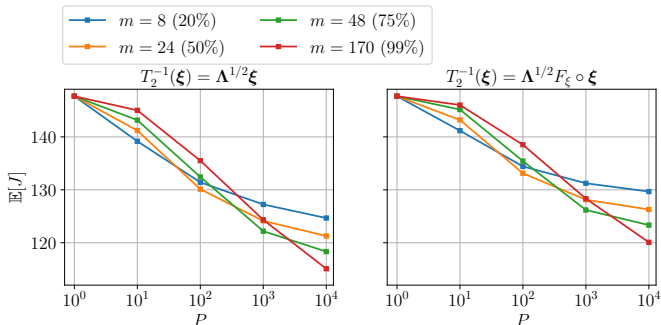
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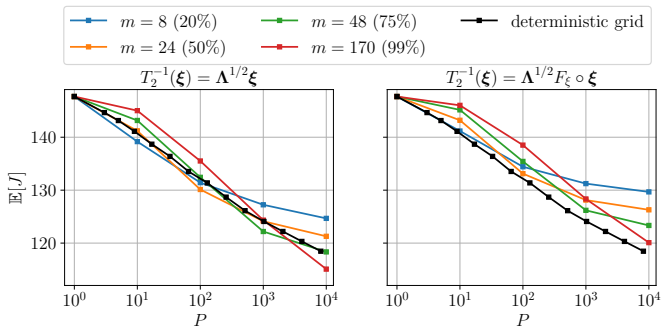
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- For some m , $\mathbb{E}[J]$ stagnates passed some value of P . The smaller m the faster it happens.
- A similar behavior is observed for $T_2^{-1}(\xi) = \Lambda^{1/2}F_\xi \circ \xi$, but with larger values of $\mathbb{E}[J]$.

Effect of preconditioning strategies from different stationary quantizers and deterministic grids

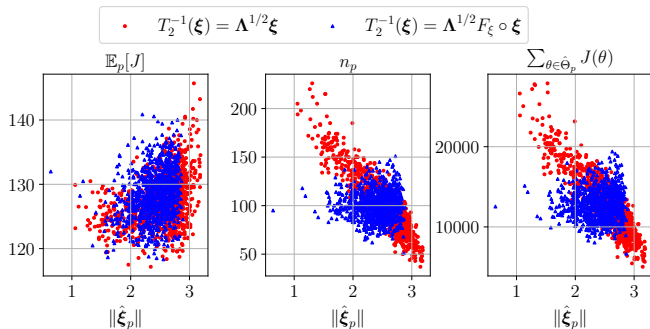
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- For some m , $\mathbb{E}[J]$ stagnates passed some value of P . The smaller m the faster it happens.
- A similar behavior is observed for $T_2^{-1}(\xi) = \Lambda^{1/2}F_\xi \circ \xi$, but with larger values of $\mathbb{E}[J]$.
- Using the deterministic grid prevents the stagnation of $\mathbb{E}[J]$.

Distribution of cumulated number of solver iterations for different stationary quantizers

- Let $\hat{T}_1^{-1}\kappa$ have $m = 8$ KL modes (for 20% energy) and $P=1,000$.
- The realizations of the simulation are denoted by $\hat{\Theta} \in \Theta$ with the partition $\hat{\Theta}_1, \dots, \hat{\Theta}_P$.
- We are interested by number of linear solves n_p per preconditioner, and the cumulated number of solver iterations $\sum_{\theta \in \hat{\Theta}_p} J(\theta)$.



- The strategy with $T_2^{-1} = \Lambda^{1/2}F_\xi \circ \xi$ is more load balanced.

Conclusions and perspectives

Conclusions:

- A lot of improvement can be made compared to using a single constant preconditioner.
- The optimal energy level of the approximating coefficient field of a preconditioning strategy based on stationary quantizers depends on P . Selecting an optimal m requires some preprocessing.
- For sequential simulations, the average number of solver iterations is minimized by letting $T_2^{-1} := \Lambda^{1/2} \xi$.
- For distributed simulations, the most balanced distribution of the cumulated number of solver iterations is obtained by letting $T_2^{-1} := \Lambda^{1/2} F_\xi \circ \xi$.
- Using a deterministic grid such that the approximating coefficient field has an energy which increases with P prevents stagnation of $\mathbb{E}[J]$ and does not require preprocessing.

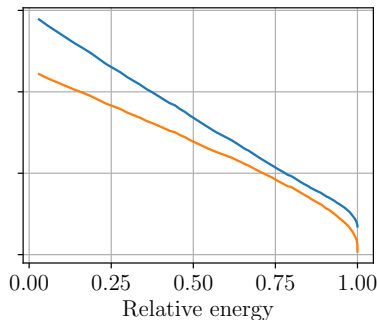
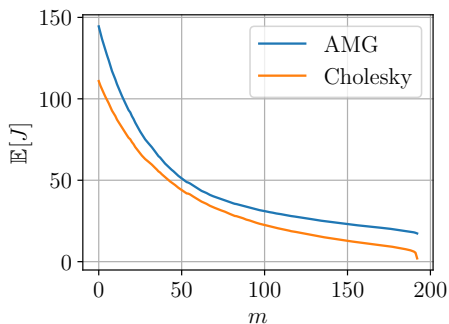
Future endeavor:

- Speeding-up the setup of AMG preconditioners for random coefficient fields when using fixed meshes and discretization.



Effect of truncation of the approximating KL expansion on realization-dependent ideal preconditioning

- ▶ Let $T_1^{-1}\kappa := \log \kappa$ be a Gaussian process with $C(x, x') = \exp\left(\frac{-\|x-x'\|^2}{0.1^2}\right)$.
- ▶ Relative energy is the variance of $\hat{T}_1^{-1}\kappa$ given by $\sum_{k=1}^m \lambda_k$.
- ▶ Discretization with 100,000 DoFs.



- ▶ AMG preconditioners are nearly as effective as Cholesky factorizations, especially for large values of relative energy.
- ▶ Nearly linear dependence of $\mathbb{E}[J]$ on relative energy.

Local interpolation of preconditioners

- Let us consider the case of distributed simulations in which the m -th node (out of $M \leq P$) stores P_m preconditioners $\mathbf{M}^{-1}(\hat{\boldsymbol{\xi}}_1^{(m)}), \dots, \mathbf{M}^{-1}(\hat{\boldsymbol{\xi}}_{P_m}^{(m)})$ in memory.
- When $\boldsymbol{\xi}$ is drawn close to a centroid of the m -th node, we follow the work of Zahm and Nouy (2016) and leverage the availability of local preconditioners to approximate $\mathbf{M}^{-1}(\boldsymbol{\xi})$ with an interpolation of the form

$$\hat{\mathbf{M}}_m^{-1}(\boldsymbol{\xi}) = \sum_{p=1}^{P_m} \alpha_p^{(m)}(\boldsymbol{\xi}) \mathbf{M}^{-1}(\hat{\boldsymbol{\xi}}_p^{(m)}).$$

- An ideal choice for $\alpha_1^{(m)}, \dots, \alpha_{P_m}^{(m)} \in \mathbb{R}$ is to minimize the condition number of $\hat{\mathbf{M}}_m^{-1}(\boldsymbol{\xi}) \mathbf{A}(\boldsymbol{\xi})$. This, however, is a Clarke regular pseudoconvex optimization problem which is not worth solving for every realization of $\boldsymbol{\xi}$.

Zahm, Olivier, and Anthony Nouy. "Interpolation of inverse operators for preconditioning parameter-dependent equations." SIAM Journal on Scientific Computing 38.2 (2016): A1044-A1074.

Local interpolation of preconditioners

► Another more computationally feasible alternative is to minimize the Frobenius norm $\|\mathbf{I} - \hat{\mathbf{M}}_m^{-1}(\boldsymbol{\xi})\mathbf{A}(\boldsymbol{\xi})\|_F$. This leads to solving

$$\mathbf{B}(\boldsymbol{\xi}) \begin{bmatrix} \alpha_1^{(m)}(\boldsymbol{\xi}) \\ \vdots \\ \alpha_{P_m}^{(m)}(\boldsymbol{\xi}) \end{bmatrix} = \begin{bmatrix} \text{tr} \left(\mathbf{M}^{-1}(\hat{\boldsymbol{\xi}}_1^{(m)})\mathbf{A}(\boldsymbol{\xi}) \right) \\ \vdots \\ \text{tr} \left(\mathbf{M}^{-1}(\hat{\boldsymbol{\xi}}_{P_m}^{(m)})\mathbf{A}(\boldsymbol{\xi}) \right) \end{bmatrix}$$

where $\mathbf{B}(\boldsymbol{\xi})$ has components

$$B_{pq}(\boldsymbol{\xi}) = \text{tr} \left(\left(\mathbf{M}^{-1}(\hat{\boldsymbol{\xi}}_p^{(m)})\mathbf{A}(\boldsymbol{\xi}) \right)^T \mathbf{M}^{-1}(\hat{\boldsymbol{\xi}}_q^{(m)})\mathbf{A}(\boldsymbol{\xi}) \right), \quad (p, q) \in [1, P_m]^2.$$

► The computation of the matrices $\mathbf{M}^{-1}(\hat{\boldsymbol{\xi}}_p)\mathbf{A}(\boldsymbol{\xi})$ for $p = 1, \dots, P_m$ requires large numbers of preconditioner applications whose cost may surpass the gain obtained by local interpolation. Random sketching is used to significantly reduce the number of necessary preconditioner applications.

► **Results:** we applied Shepard interpolation and the minimizer presented here with and without random sketching to build local interpolations of preconditioners. All of our attempts failed to improve convergence.

